

# **RC-04D**

**IQRF Programmable remote controller**

## **User's Guide**



## Description

RC-04D is a universal user programmable IQRF remote controller with bidirectional communication.

It is a generic equipment, i.e. the hardware is fixed and the user can implement specific functionality by software for internal microcontroller. The code can be uploaded wirelessly.



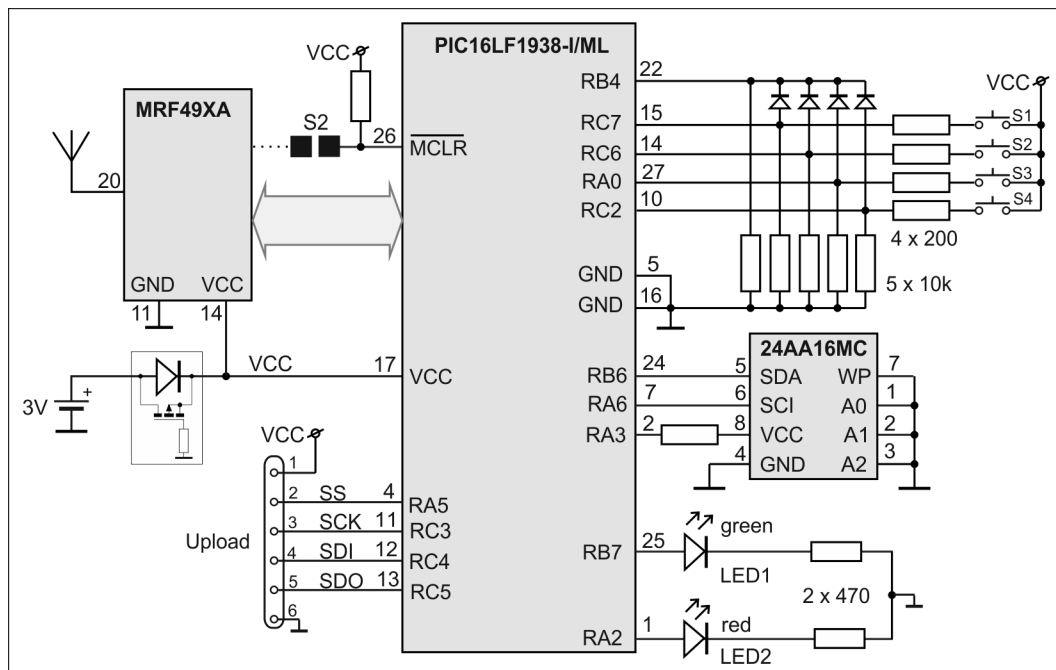
## Applications

- Portable controller
- Any systems with IQRF connectivity
- Wide usage facilities

## Key features

- Built-in IQRF transceiver module
- Programmable via RF
- Architecture based on TR-56D
- On-board PCB antenna
- 4 pushbuttons, 2 LEDs
- Bidirectional communication – high security in comparison to unidirectional systems
- Sleep mode with ultra low power consumption
- Coin battery

## Simplified schematic



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**Electrical specifications****Typical values unless otherwise stated**

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RF transceiver	Built-in, based on the TR-56D architecture
RF IC	MRF49XA (Microchip)
Microcontroller	PIC16LF1938 (Microchip)
Antenna	PCB shortened ¼ wave whip
Frequency band	868 MHz or 916 MHz, multiple channels (SW selectable)
RF output power	Up to 3.5 mW, programmable in 7 steps
Battery	Lithium 3V, 210 mAh coin cell CR2032
Supply current	<i>Depends on application SW (see TR-56D datasheet for details)</i>
Sleep mode	0.8 µA (all peripherals shut down)
Additional watchdog supply current	2 µA typ., 4 µA max. (watchdog enabled)
Run mode	1 mA @ 8 MHz (RF circuitry in standby mode)
Additional supply current	0.6 mA (RF circuitry on) 2 mA (one LED on), 4 mA (two LEDs on)
Rx mode	
STD mode	13 mA
LP mode	330 µA (depends on interferences)
XLP mode	25 µA (depends on interferences)
Tx mode	14 mA – 24 mA (according to RF output power)
RF range	up to 240 m (in free space)
Operating temperature	-20 °C to +40 °C, with respect to the battery operating conditions
Dimensions	58 mm x 42 mm x 14 mm
Weight	29 g (with the battery and the charm chain)

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**Absolute maximum ratings**

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Stresses above those values may cause permanent damage to the device. Exposure to maximum rating conditions for extended periods may affect device reliability.

Supply voltage (VCC)	3.5 V
Storage temperature	-20 °C to +85 °C, with respect to the battery storing conditions

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**Hardware**

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RC-04D is a generic equipment, i.e. the hardware is fixed and specific functionality can be implemented by software for integrated transceiver module.

**Power supply**

RC-04D is supplied from the coin non-rechargeable battery.

**Sleep mode**

It is possible to switch off all functions and peripherals to minimize current. For Sleep mode control refer to demo software included. The power can not be switched off at all (unless removing the battery), the Sleep mode should be used instead of this.

**Tip:** User SW should allow wake-up the controller after pushbutton(s) press. See demo SW included.

**Pushbuttons and LEDs**

Functionality of all four pushbuttons and both LEDs is fully under control of application software.

**RF transceiver**

Integrated IQRF wireless transceiver based on the TR-56D architecture.

- Uploading of application code is possible via IQRF wireless upload.
- Pads for wired upload via SPI accessible on the PCB board are intended for troubleshooting only. See the silkscreen on the PCB for pinout description.
  - Using the CK-USB-04A programmer: See the CK-USB-04A User's guide.
  - Using the CK-USB-04 programmer and the KON-TR-01P adapter. See the KON-TR-01P User's guide.

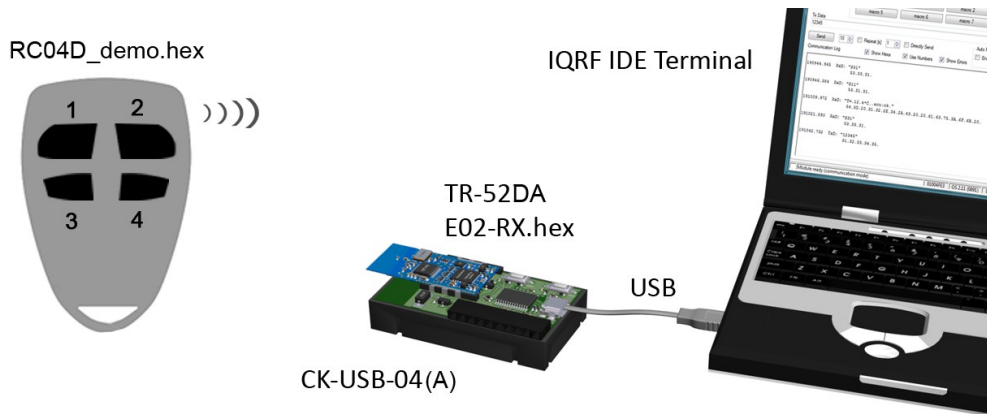
**Antenna**

Built-in PCB antenna on the RC-04 board.

## Software

### Demo application

This demo illustrates unidirectional non-networking communication between the RC-04D controller and the CK-USB-04(A) kit equipped with the TR-52DA module connected to PC with the IQRF IDE Terminal running. The RC04D\_demo.c program is intended for the controller and the E02-RX (one of basic IQRF examples) for the TR module in the CK kit. They are available to download on RC-04D product page and in IQRF Startup package, respectively. To upload the RC04\_demo.hex to the RC-04D via RF, see the IQRF OS User's guide, Appendix RFPGM. Switching to RFPGM mode after reset is enabled by default.



In idle state the controller stays in Sleep mode allowing wake-up by any pushbutton. After wake-up the battery voltage is checked and LEDs flashing indicates pressing the button and accumulator condition. Then respective command is sent to CK-USB-04(A) and the controller gets to sleep again.

Buttons	Function	
• S1	Text sent: "S1x"	x=0 if battery O.K., otherwise x=1
• S2	Text sent: "S2x"	..-
• S3	Text sent: "S3x"	..-
• S4	Text sent: "S4x"	..-
• S3 and S4 for more than 5 s	Enter RFPGM mode	
• Any button for more than 0.7 s	Leave RFPGM mode	

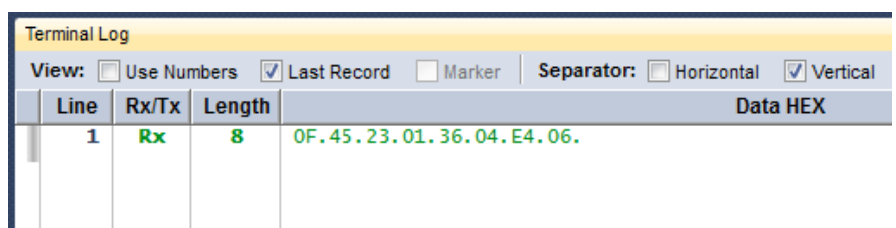
LED indication	
• Button S1 to S4	1 x flash green (battery O.K.) / red (battery exhausted).
• RFPGM indication	See the IQRF OS User's guide, Appendix RFPGM, indication in RFPGM LP mode.

**Caution:** Demo software version should correspond to IQRF OS version implemented in RC-04D.

To read out the OS version, catch Module Info which is always sent by this Demo application just before switching to RFPGM mode in IQRF IDE Terminal. The *Show hexa* checkbox should be activated for this. OS version is stored in buffer `moduleINFO[4]`. See the picture above and IQRF OS User's guide.

#### Example:

```
moduleINFO[0-7]:
[0] [1] [2] [3] [4] [5] [6] [7]
3C 5D 00 01 30 03 39 11
0F 45 23 01 36 04 E4 06
moduleINFO[4] = 36 means OS v3.06D
```



**Caution**

The only standard way how to upload user application into the RC-04D is RFPGM (wireless programming, ICWP). Demo application `RC04D_demo.c` invokes the `enableRFPGM` function first. It ensures that after every reset (due to reconnecting the battery) the device is switched to RFPGM mode and can possibly be reprogrammed. This feature can be removed (by `disableRFPGM`), but it should not be done unless there is another reliable way how to invoke back the RFPGM mode using `runRFPGM` after pressing a pushbutton. See the demo application, refer to the IQRF OS User's guide, Appendix RFPGM for details. **If being omitted, the device can not be reprogrammed wirelessly any more. Recovery is possible by wired upload using the PCB pads inside the case only.**

**Tip:** Always use `enableRFPGM` during development.

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**Product information**

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**Pack list**

- RC-04D remote controller with charm chain, battery inserted, the `RC04D_demo` demo uploaded, in Sleep mode

**Recommended options**

- CK-USB-04(A) Programmer / development kit for wireless upload (RFPGM)
- TR-52DA Additional TR module for the CK-USB-04(A) for wireless upload (RFPGM)
- CAB-USBABMICRO USB cable to connect CK-USB-04(A) to PC
- GW-USB-05 Complete comfortable RFPGM programmer (alternative to all above)

**Ordering code**

- RC-04D RC-04D Remote controller

**Document history**

- 160519 TR compatibility explanation slightly corrected
- 141105 First release

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# Sales and Service

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*Complies with ETSI directives EN 301489-1 V1.9.2:2011, EN 301489-3 V1.6.1:2013, EN 300220-1 V2.4.1:2012, EN 300220-2 V2.4.1:2012 and VO-R/10/04.2012-7.*

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