

IQRF OS

Operating System

**Version 3.05D
for TR-5xD**

Reference Guide



Quick reference

Values between system functions and superordinate program are passed on via parameters. OS uses 3 parameters in total: `param2` (1 B), `param3` (2 B) and `param4` (2 B). Their location in memory see the RAM map [2]. Individual functions have up to 3 parameters. Several functions use some of these params and W (PIC accumulator) to return output values. Note that they are valid until another function using the same parameter or the `debug` function is called by the user. Additionally, some functions use some params as work variables that is why their previous content can be destroyed.

Five stack levels are available to call all OS functions in subroutines.

Unless otherwise stated, OS functions run in OS foreground. Thus, the program continues not until the function is finished.

Several functions, e.g. `startSPI(x)` or `startDelay(x)` run in OS background. Thus, the program continues immediately further and the user can check the result later on.

Functions

Unless otherwise stated, all functions are the *void* type and all their parameters are the *uns8* type.

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OS functions
Control
calibrateTimer

Function	Calibrate tick generator
Purpose	–
Syntax	<code>void calibrateTimer()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Do not use this function. It is not necessary to calibrate IQMESH timing from OS v3.01D.
Remarks	–
Side effects	–
See also	–
Example	–

Obsolete

iqrfsleep

Function	Setting the TR module in power saving mode (Sleep)
Purpose	Easy and efficient power management. This function, once called, puts the module into the Sleep mode. Wake-up can be caused by power off/on, watchdog timeout or on the C5 (for TR modules in SIM format, e.g. TR-52D) or Q12 (for TR-54D) pin change.
Syntax	<code>void iqrfsleep ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • This functions operates like the PIC machine instruction Sleep. Additionally, OS suspends all HW resources that are under its control (RF circuitry, timers, internal PIC pins, LEDs including their background activities, see Example 4 etc.). The user should do the same for resources used by the application before entering the Sleep mode to achieve minimal power consumption. • For wake-up on pin change the required sequence should be executed. Wake-up on pin change is default disabled. • This function is not time-efficient for subsequent short sleep periods, especially if RF IC is off. For faster operation in such cases use <code>sleep()</code> instead but you should ensure minimal consumption by user program. See Example 3.
Remarks	All features are under user's control. RBIF flag is not cleared to allow to distinguish wake-up type. See example E01-TX [10].
Side effects	Global interrupt enable (GIE) is controlled by OS again after wake-up.
See also	<code>setRFsleep</code>
Example 1	<pre> // Minimize consumption (depends on resources used by the user) Motor = 0; // Stop the motor ADON = 0; // Disable A/D converter SWDTEN = 0; // Disable watchdog iqrfsleep(); // Put the module into Sleep mode </pre>
Example 2	<pre> // Wake-up on pin change. See example E01-TX and IQRF-macros.h header file. GIE = 0; // Disable all interrupts writeToRAM(&IOCBN, IOCBN 0x10); // Negative edge active. // Instead of IOCBN.4=1; // Bit IOCBN.4 cannot be accessed // directly due to OS restriction. IOCBP.4 = 1; // Positive edge active IOCFIE = 1; // Interrupt on change enabled SWDTEN = 0; // Watchdog disabled iqrfsleep(); // Sleep writeToRAM(&IOCBF, IOCBF & 0xEF); // Clear interrupt on change flag. // Instead of IOCBF.4=0; // Bit IOCBF.4 cannot be accessed // directly due to OS restriction. if (buttonPressed) // If button is pressed { ... } // ... </pre>
Example 3	<pre> iqrfsleep(); // Sleep // Wake-up, RF IC remains off ... stopLEDR(); // Disable peripherals to minimize consumption sleep(); // Faster (if RF IC is off). This is not an IQRF function // but a machine instruction supported by C compiler. pulseLEDR(); // Continue after wake-up </pre>
Example 4	<pre> pulseLEDR(); // Background LED activity should be stopped before sleep waitDelay(50); // e.g. by waiting until the LED is off otherwise the LED iqrfsleep(); // may unintentionally be switched on during sleep. </pre>

setRFsleep

Function	Setting RF circuitry in power saving mode (Sleep)
Purpose	To put all RF circuitry in Sleep mode. Easy and efficient power management.
Syntax	<code>void setRFsleep ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • RF IC is set off. • OS system clock (ticks) are derived from MCU internal RC oscillator instead of precise RF IC crystal.
Preconditions	–
Remarks	0.6 mA typ. is saved. RF response is prolonged for 2 ms typ., 7 ms max. due to wake-up. Wake-up can be caused by <code>setRFready</code> , <code>RFTXpacket</code> , <code>RFRXpacket</code> , <code>checkRF</code> or <code>getSupplyVoltage</code> .
Side effects	–
See also	<code>setRFready</code> , <code>iqrfSleep</code> , <code>getSupplyVoltage</code> , <code>checkRF</code> , <code>RFTXpacket</code> , <code>RFRXpacket</code>
Example	<code>setRFsleep(); // Put the RF circuitry in Sleep mode</code>

setRFready

Function	Wake RF circuitry up
Purpose	To wake RF circuitry up in advance for faster response, easy and efficient power management and precise ticks.
Syntax	<code>void setRFready ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • RF IC is set on (the RF ready mode) but RX chain still stays off (unlike the RX mode). See IQRF User's guide, RF IC modes. • RF IC crystal oscillator starts up. • OS system clock (tick) is based on precise RF IC crystal oscillator instead of MCU internal RC one.
Preconditions	–
Remarks	Takes ~7 ms. After this time the RX chain can be set on faster which enables faster <code>checkRF(x)</code> , <code>RFRXpacket()</code> or <code>RFTXpacket()</code> .
Side effects	–
See also	<code>setRFsleep</code> , <code>iqrfSleep</code> , <code>getSupplyVoltage</code> , <code>checkRF</code> , <code>RFTXpacket</code> , <code>RFRXpacket</code>
Example	<pre>setRFready(); // Wake the RF circuitry up from RF sleep in advance ... RFTXpacket(); // for immediate response</pre>

debug

Function	Enter the debug mode
Purpose	IQRF OS directly supports debugging and testing. It is possible to stop the application wherever you need and display internal values (variables, RAM registers, EEPROM etc.) and then continue later on.
Syntax	<code>void debug ()</code>
Parameters	–
Return value	–
Output values	OS directly returns no value but supports using W (PIC accumulator) to identify which of the debug points is currently active.
Preconditions	<ul style="list-style-type: none"> • Debug should be used with corresponding development kit (e.g. CK-USB-04) and the IQRF IDE development environment. • To avoid possible HW collision with respect to user application, <code>debug</code> operates only under the following conditions: <ul style="list-style-type: none"> • Pins C5 to C8 are configured for SPI slave in respective TRIS bits (C8 out, the others in). It is arranged by OS by default. • The <i>Check Mode</i> function is enabled in IQRF IDE. Otherwise no communication on these pins is initiated by debug tools even though TR is in debug mode until the <i>Check Mode</i> is enabled. • SPI need not be enabled by <code>enableSPI</code>
Remarks	Number of <code>debug()</code> instances is unlimited. The application is running until a <code>debug</code> function is encountered. Then the program is stopped and the module is switched to the debug mode allowing IQRF IDE to display values. The module stays in the debug mode until the user selects the <i>Skip Breakpoint</i> button. Then the application program continues running until another <code>debug</code> function is encountered and so on. See IQRF IDE Help and example E04-EEPROM [10].
Side effects	<ul style="list-style-type: none"> • <code>param1</code> to <code>param4</code> are not displayed • Watchdog is cleared while in Debug mode
See also	–
Example	<pre>if (compareBufferINFO2RF(4)) W = 1; // match else W = 2; // mismatch debug(); // Skip Debug 1 or 2 will be displayed here according the result</pre>

getSupplyVoltage

Function	Power supply measurement (up to 3.8 V)
Purpose	Battery check (for discharge-sensitive batteries)
Syntax	<code>uns8 getSupplyVoltage ()</code>
Parameters	–
Return value	<code>level = 1, 2, ...15</code> <code>Voltage > 2.25 V + level × 0.1 V</code>
Output values	–
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Internal power supply voltage is checked. • In case of TR modules with LDO it is the LDO output but not actual battery voltage. This value is 3.0 V typ. if battery is O.K. and drops down if battery is low. • To evaluate the battery, take into consideration your battery type and power supply circuitry with respect to diodes and other possible voltage drops. • The detector circuit has a built-in 50 mV hysteresis.
Side effects	The RF circuitry wakes up (in case of sleeping).
See also	<code>setRFsleep</code>
Example	<pre> if (getSupplyVoltage () < 7) ... // Low battery else ... // Voltage > 2.95V </pre>

getTemperature

Function	Read temperature from on-board sensor																														
Purpose	Temperature measurement																														
Syntax	uns8 getTemperature ()																														
Parameters	–																														
Return value	<ul style="list-style-type: none"> • Temperature in °C, integer part, not rounded • Negative temperatures are in two's complement format (e.g. 0xFFB means -5 °C) • 0x80 (-128 °C). For TR modules without temperature sensor, i.e. without the "T" postfix, e.g. TR-52D. 																														
Output values	<p>param3: complete 12 b output value of the sensor in 0.0625 °C units. Thus, lower 4 b represent the fractional part and upper 8 b represent the integer part of temperature. Negative temperatures are in two's complement format. See datasheet of the sensor.</p> <p>Examples:</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Temperature</th> <th>Return value</th> <th>param3</th> <th>Temperature</th> <th>Return value</th> <th>param3</th> </tr> </thead> <tbody> <tr> <td>50 °C</td> <td>0x32</td> <td>0x320</td> <td>0 °C</td> <td>0x00</td> <td>0x000</td> </tr> <tr> <td>5 °C</td> <td>0x05</td> <td>0x050</td> <td>-0.5 °C</td> <td>0xFF</td> <td>0xFF8</td> </tr> <tr> <td>5.5 °C</td> <td>0x05</td> <td>0x058</td> <td>-1 °C</td> <td>0xFF</td> <td>0xFF0</td> </tr> <tr> <td>0.75 °C</td> <td>0x00</td> <td>0x00C</td> <td>-8 .25 °C</td> <td>0xF7</td> <td>0xF7C</td> </tr> </tbody> </table>	Temperature	Return value	param3	Temperature	Return value	param3	50 °C	0x32	0x320	0 °C	0x00	0x000	5 °C	0x05	0x050	-0.5 °C	0xFF	0xFF8	5.5 °C	0x05	0x058	-1 °C	0xFF	0xFF0	0.75 °C	0x00	0x00C	-8 .25 °C	0xF7	0xF7C
Temperature	Return value	param3	Temperature	Return value	param3																										
50 °C	0x32	0x320	0 °C	0x00	0x000																										
5 °C	0x05	0x050	-0.5 °C	0xFF	0xFF8																										
5.5 °C	0x05	0x058	-1 °C	0xFF	0xFF0																										
0.75 °C	0x00	0x00C	-8 .25 °C	0xF7	0xF7C																										
Preconditions	<ul style="list-style-type: none"> • Applicable for TR modules with TMP112 (TI) temperature sensor only (e.g. not for TR-58D-RJ). • 100 ms delay is required after wake up from sleep 																														
Remarks	<ul style="list-style-type: none"> • Resolution 0.0625 °C, accuracy: 0.5 °C • Takes ~1.7 ms • See example E08–TEMPERATURE [10] 																														
Side effects	–																														
See also	–																														
Example 1	<pre> // For positive temperatures only uns8 tempInt; // Temperature, integer part uns8 tempFract; // Temperature, fractional part tempInt = getTemperature(); tempFract = param3.low8 & 0x0F // Temperature == tempInt + tempFract/16 // Temperature == param3 * 0.0625 in °C </pre>																														
Example 2	<pre> // Either positive or negative temperatures, fractional part ignored T = getTemperature(); // Integer part of temperature if (T >= 0x80) { sign = "-"; // Negative T = (T ^ 0xFF) + 1; // Get absolute value in °C } else sign = "+"; // Positive </pre>																														
Example 3	<pre> // Either positive or negative temperatures, with fractional part if (getTemperature() >= 0x80) { sign = "-"; // Negative T = (param3 ^ 0xFFF) + 1; // Get absolute value, in 0.0625°C units } else sign = "+"; // Positive </pre>																														
Example 4	<pre> // Temperature measurement after wake-up from sleep iqrfsleep(); waitDelay(10); // 100 ms delay required T = getTemperature(); </pre>																														

Active waiting

waitMS

Function	Wait specified number of miliseconds
Purpose	Time delay generation
Syntax	<code>void waitMS (ms)</code>
Parameters	ms - time to wait in miliseconds (1 - 255)
Return value	–
Output values	–
Preconditions	This function can be combined with <code>waitDelay</code> , <code>startCapture</code> and <code>captureTicks</code> .
Remarks	This is an active waiting (on OS foreground). No other operation runs on OS foreground during waiting. Time precision depends on internal RC oscillator. Thus, the delay can vary with temperature etc. See respective PIC datasheet [8].
Side effects	–
See also	<code>waitDelay</code> , <code>startDelay</code> , <code>startLongDelay</code>
Example	<pre>waitMS(10); // Delay 10 ms. Program stays here for the whole 10 ms period ... // and continues here just after the period elapsed.</pre>

waitDelay

Function	Wait specified number of ticks
Purpose	Time delay generation
Syntax	<code>void waitDelay (ticks)</code>
Parameters	ticks – time to wait in 10 ms periods (1 - 255)
Return value	–
Output values	–
Preconditions	This function can be combined with <code>waitMS</code> .
Remarks	This is the active waiting (on OS foreground). No other operation runs on OS foreground during waiting.
Side effects	<ul style="list-style-type: none"> • This function must not be combined with <code>startDelay</code> and <code>startLongDelay</code>. • Internal ticks are based on internal RC oscillator. Thus, the delay can vary with temperature etc. See respective PIC datasheet [8]. • Delay in first tick can vary from 0 ms to 10 ms. If complete 10 ms is needed also in the first tick, use <code>waitNewTick</code> firstly. • For short time delays <code>waitMS</code> is more precise.
See also	<code>waitMS</code> , <code>startDelay</code> , <code>startLongDelay</code>
Example 1	<pre> // LED on for 0.5 s _LED = 1; waitDelay(50); // Delay 500 ms. Program stays here for 500 ms _LED = 0; // and continues here just after the period elapsed.</pre>

waitNewTick

Function	Wait for a new tick
Purpose	Timing synchronization of user operations
Syntax	<code>void waitNewTick ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	–
Remarks	Active waiting (on OS foreground) until a new tick starts. No other operation runs on OS foreground during this waiting.
Side effects	–
See also	<code>waitMS</code> , <code>waitDelay</code>
Example	<pre>waitNewTick(); // To generate a pulse as precise as possible IO1 = 1; waitDelay(1); // 10 ms IO1 = 0;</pre>

Timing on background

startCapture

Function	Reset and start the Capture timer
Purpose	Initialization of time measurement or delay generation
Syntax	<code>void startCapture ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	This function can be combined with <code>waitMS</code> .
Remarks	Capture timer is a resettable counter of OS ticks (10 ms system intervals) running on OS background. This function clears the counter and starts counting.
Side effects	Functionality is affected by <code>bondRequest</code> , <code>bondNewNode</code> , <code>RFRXpacket</code> and <code>RFTXpacket</code> .
See also	<code>captureTicks</code>
Example	See <code>captureTicks</code>

captureTicks

Function	Get number of ticks counted from the last <code>startCapture</code> and <code>captureTicks</code> calling.
Purpose	Measurement of elapsed time.
Syntax	<code>void captureTicks ()</code>
Parameters	–
Return value	–
Output value	<ul style="list-style-type: none"> • param3: ticks counted from the last <code>startCapture</code> (0 - 65535) • param4: ticks counted from the last <code>captureTicks</code> (0 - 65535)
Preconditions	<ul style="list-style-type: none"> • <code>startCapture</code> should be used at least once before. • To ensure correct operation the counter must not overflow. That is why <code>captureTicks</code> should be called max. ~655 s after last <code>startCapture</code> or <code>captureTicks</code> calling.
Remarks	See example E05–DELAYS [10]
Side effects	<ul style="list-style-type: none"> • Functionality is affected by <code>bondRequest</code>, <code>bondNewNode</code>, <code>RFRXpacket</code> and <code>RFTXpacket</code>. • Internal ticks are based on internal RC oscillator if RF IC is sleeping. Thus, the delay can vary with temperature etc. in this case. See respective PIC datasheet [8].
See also	<code>startCapture</code> , <code>setRFready</code>
Example	<pre>startCapture(); // Reset counter of ticks waitMS(200); // Delay 200 ms captureTicks(); // param3 == 20 waitMS(150); // Delay 150 ms captureTicks(); // param3 == 35, param4 == 15 startCapture(); // Reset counter of ticks waitMS(100); // Delay 100 ms captureTicks(); // param3 == 10</pre>

startDelay

Function	Preset and start the Delay timer
Purpose	Initialization of time measurement or delay generation
Syntax	void startDelay (ticks)
Parameters	uns8 ticks: number of ticks (10 ms system intervals) to be measured (1-255)
Return value	–
Output values	–
Preconditions	This function can be combined with <code>waitMS</code> and <code>startLongDelay</code> .
Remarks	The Delay timer measures specified time period on OS background. The result is available via the <code>isDelay</code> function.
Side effects	<ul style="list-style-type: none"> • This function does not work properly if the <code>waitDelay</code> or <code>startLongDelay</code> functions are active. • Functionality is affected by <code>bondRequest</code>, <code>bondNewNode</code>, <code>RFRXpacket</code> and <code>RFTXpacket</code>. • Delay in first tick can vary from 0 ms to 10 ms. If complete 10 ms is needed also in the first tick, use <code>waitNewTick</code> firstly. • Internal ticks are based on internal RC oscillator if RF IC is sleeping. Thus, the delay can vary with temperature etc. in this case. See respective PIC datasheet [8].
See also	<code>isDelay</code> , <code>startLongDelay</code> , <code>waitDelay</code>
Example	See <code>isDelay</code>

startLongDelay

Function	Preset and start the LongDelay timer
Purpose	Initialization of time measurement or delay generation
Syntax	void startLongDelay (ticks)
Parameters	uns16 ticks: number of ticks (10 ms system intervals) to be measured (1-65535)
Return value	–
Output values	–
Preconditions	This function can be combined with <code>waitMS</code> and <code>startDelay</code> .
Remarks	The Delay timer measures specified time period on OS background. The result is available via the <code>isDelay</code> function.
Side effects	<ul style="list-style-type: none"> • This function does not work properly if the <code>waitDelay</code> or <code>startLongDelay</code> functions are active. • Functionality is affected by <code>bondRequest</code>, <code>bondNewNode</code>, <code>RFRXpacket</code> and <code>RFTXpacket</code>. • Delay in first tick can vary from 0 ms to 10 ms. If complete 10 ms is needed also in the first tick, use <code>waitNewTick</code> firstly. • Internal ticks are based on internal RC oscillator if RF IC is sleeping. Thus, the delay can vary with temperature etc. in this case. See respective PIC datasheet [8].
See also	<code>isDelay</code> , <code>startDelay</code> , <code>waitDelay</code>
Example	See <code>isDelay</code>

isDelay

Function	Information whether specified delay is still in progress
Purpose	Time measurement or delay generation
Syntax	bit <code>isDelay()</code>
Parameters	–
Return value	<ul style="list-style-type: none"> • 1: still in progress • 0: elapsed
Output values	–
Preconditions	<code>startDelay</code> or <code>startLongDelay</code> should be used before.
Remarks	<ul style="list-style-type: none"> • The (Long)Delay timer measures specified time period. The result is available via the <code>isDelay</code> function. • Tip: the <code>clrwdt</code> instruction should be used to avoid unintentional watchdog reset during the delay. • See example E05-DELAYS [10].
Side effects	–
See also	<code>startDelay</code> , <code>startLongDelay</code>
Example 1	<pre> // LED on for 1 s _LED = 1; startDelay(100); // Start 1 sec delay counting on OS background while (isDelay()) // Wait until the delay is over { clrwdt(); // Any useful operation on OS foreground can be ... // performed during waiting } _LED = 0; // Continue here after 1 sec </pre>
Example 2	<pre> // LED on for 10 s _LED = 1; startLongDelay(1000); // Start 10 sec delay counting on OS background while (isDelay()) // Wait until the delay is over { clrwdt(); // Any useful operation on OS foreground can be ... // performed during waiting } _LED = 0; // Continue here after 10 sec </pre>

LED indication

setOnPulsingLED

Function	LEDs On time setting (red as well as green)
Purpose	Specification of the "On" time for LEDs (either for a single flash or for blinking)
Syntax	<code>void setOnPulsingLED (ticks)</code>
Parameters	<code>uns8 ticks</code> : number of ticks (10 ms system intervals) (1-255)
Return value	–
Output values	–
Preconditions	–
Remarks	Default value is 5 (50 ms).
Side effects	–
See also	<code>setOffPulsingLED</code> , <code>pulsingLEDR</code> , <code>pulseLEDR</code> , <code>pulsingLEDG</code> , <code>pulseLEDG</code>
Example	See <code>setOffPulsingLED</code>

setOffPulsingLED

Function	LEDs Off time setting (red as well as green)
Purpose	Specification of the "Off" time for LEDs (for blinking)
Syntax	<code>void setOffPulsingLED (ticks)</code>
Parameters	<code>uns8 ticks</code> : number of ticks (10 ms system intervals) (1-255)
Return value	–
Output values	–
Preconditions	–
Remarks	Default value is 20 (200 ms).
Side effects	–
See also	<code>setOnPulsingLED</code> , <code>pulsingLEDR</code> , <code>pulsingLEDG</code>
Example	<pre> // Change blinking to 250 ms On / 750 ms Off setOnPulsingLED(25); // 250 ms On setOffPulsingLED(75); // 750 ms Off </pre>

pulsingLEDR

Function	Red LED blinking
Purpose	Continuous red LED blinking on OS background
Syntax	<code>void pulsingLEDR()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Blinking times should be defined in advance by <code>setOnPulsingLED</code> and <code>setOffPulsingLED</code>. • The appropriate PIC pin is configured as an output automatically. • Do not combine this function with direct access to LED pin (see <code>pulseLEDR</code> <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	<ul style="list-style-type: none"> • Blinking continues until it is stopped by the user (e.g. by <code>stopLEDR</code>).
Side effects	–
See also	<code>setOnPulsingLED</code> , <code>setOffPulsingLED</code> , <code>stopLEDR</code> , <code>pulseLEDR</code>
Example 1	<code>pulsingLEDR(); // continuous blinking on OS background</code>
Example 2	<pre>// Blinking for 2 s pulsingLEDR(); // blinking for 2 s on OS background waitDelay(200); // 2 s delay generated on foreground stopLEDR(); // Stop blinking</pre>

pulseLEDR

Function	Single red LED flash
Purpose	Red LED flash on OS background
Syntax	<code>void pulseLEDR()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Flash time should be defined in advance by <code>setOnPulsingLED</code>. • The appropriate PIC pin is configured as an output automatically. • Do not combine this function with direct access to LED pin (see <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	The on-board LEDs can also be directly controlled on OS foreground using C commands for manipulating the <code>_LEDR</code> output (the pin the red LED is connected to) and corresponding control bit (<code>TRISx.x</code> - see <code>IQRF-memory.h</code> header file), e.g. <code>_LEDR = 1</code> .
Side effects	–
See also	<code>setOnPulsingLEDR</code> , <code>pulsingLEDR</code> , <code>stopLEDR</code>
Example	<pre>setOnPulsingLED(10); // 100 ms On pulseLEDR(); // Single red LED flash for 100 ms on OS background ... // Program continues immediately, // not waiting until the delay expires. // LED will be switched off after 100 ms automatically</pre>

stopLEDR

Function	Red LED off, blinking stopped
Purpose	Stops the red LED activity on OS background
Syntax	<code>void stopLEDR ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Do not combine this function with direct access to LED pin (see <code>pulseLEDR</code> <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	–
Side effects	–
See also	<code>pulsingLEDR</code> , <code>pulseLEDR</code>
Example 1	<pre>pulsingLEDR (); // Start blinking on OS background ... // Blinking continues during any operation stopLEDR (); // Stop blinking</pre>
Example 2	<pre>pulseLEDR (); // Red LED On on OS background ... // continuously lighting during any operation // until specified time expired stopLEDR (); // or LED is switched Off by this command</pre>
Example 3	<pre>_LEDR = 1; // LEDR on ... stopLEDR (); // LEDR off</pre>

pulsingLEDG

Function	Green LED blinking
Purpose	Continuous green LED blinking on OS background
Syntax	<code>void pulsingLEDG ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Blinking times should be defined in advance by <code>setOnPulsingLED</code> and <code>setOffPulsingLED</code>. • The appropriate PIC pin is configured as an output automatically. • Do not combine this function with direct access to LED pin (see <code>pulseLEDG</code> <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	Blinking continues until it is stopped by the user (e.g. by <code>stopLEDG</code>).
Side effects	–
See also	<code>setOnPulsingLED</code> , <code>setOffPulsingLED</code> , <code>stopLEDG</code> , <code>pulseLEDG</code>
Example 1	<pre>pulsingLEDG (); // continuous blinking on OS background</pre>
Example 2	<pre>// Blinking for 2 s pulsingLEDG (); // blinking for 2 s on OS background waitDelay(200); // 2 s delay generated on foreground stopLEDG (); // Stop blinking</pre>

pulseLEDG

Function	Single green LED flash
Purpose	Green LED flash on OS background
Syntax	void pulseLEDG ()
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> Flash time should be defined in advance by <code>setOnPulsingLED</code>. The appropriate PIC pin is configured as an output automatically. Do not combine this function with direct access to LED pin (see <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	The on-board LEDs can also be directly controlled on OS foreground using C commands for manipulating the <code>_LEDG</code> output (the pin the green LED is connected to) and corresponding control bit (<code>TRISx.x</code> - see <code>IQRF-memory.h</code> header file), e.g. <code>_LEDG = 1</code> .
Side effects	–
See also	<code>setOnPulsingLEDG</code> , <code>pulsingLEDG</code> , <code>stopLEDG</code>
Example	<pre>setOnPulsingLEDG(10); // 100 ms On pulseLEDG(); // Single green LED flash for 100 ms on OS background ... // Program continues immediately, // not waiting until the delay expires. // LED will be switched off after 100 ms automatically</pre>

stopLEDG

Function	Green LED off, blinking stopped
Purpose	Stops the green LED activity on OS background
Syntax	void stopLEDG ()
Parameters	–
Return value	–
Output values	–
Preconditions	Do not combine this function with direct access to LED pin (see <code>pulseLEDG</code> <i>Remarks</i>). If omitted, the pin state can be modified in background.
Remarks	–
Side effects	<ul style="list-style-type: none"> The appropriate PIC pin is not restored to the state before <code>pulsingLEDG/pulseLEDG</code> (<code>TRISx.x == 0</code>, <code>_LEDG == 0</code> after finishing on background). Possible user <code>LEDR</code> pin level (in <code>PORT</code> or <code>LATCH</code> register) changed in foreground can be overridden in background.
See also	<code>pulsingLEDG</code> , <code>pulseLEDG</code>
Example 1	<pre>pulsingLEDG(); // Start blinking on OS background ... // Blinking continues during any operation stopLEDG(); // Stop blinking</pre>
Example 2	<pre>pulseLEDG(); // Green LED On on OS background ... // continuously lighting during any operation // until specified time expired stopLEDG(); // or LED is switched Off by this command</pre>

MCU EEPROM
eeReadByte

Function	Read one byte from specified location in EEPROM
Purpose	Access to EEPROM
Syntax	<code>uns8 eeReadByte (addr)</code>
Parameters	<code>uns8 addr</code> : address in EEPROM (0 to 0xBF). See EEPROM map [2].
Return value	<ul style="list-style-type: none"> • Value (0 to 255) read from specified EEPROM location • 0 when attempted to read from address 0xC0 or higher
Output values	–
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Direct user access to EEPROM (using registers <code>EECONx</code> etc.) is not allowed for security reasons, specialized OS functions are intended for this. • EEPROM area dedicated to OS (locations 0xC0 or higher) is not accessible. See example E04–EEPROM [10].
Side effects	–
See also	<code>eeReadData</code> , <code>eeWriteByte</code> , <code>eeWriteData</code>
Example 1	<code>i = eeReadByte(0); // store 1 byte from EEPROM from address 0 to i</code>
Example 2	<code>// Illegal access: Avoid access to EEPROM locations 192 (0xC0) or higher i = eeReadByte(200); // Reading from protected area is redirected to 160 (0xA0)</code>

eeReadData

Function	Read a block of specified length from specified location in EEPROM to <code>bufferINFO</code>
Purpose	Block access to EEPROM
Syntax	<code>void eeReadData (addr, length)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 addr</code>: address in EEPROM (0 to 0xBF - length + 1). See EEPROM map [2]. • <code>uns8 length</code>: number of bytes to be read (1 to 32)
Return value	–
Output values	<ul style="list-style-type: none"> • <code>bufferINFO[0 to length - 1]</code> • <code>bufferINFO[0 to length - 1]</code> is cleared when attempted to read from address 0xC0 or higher
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Direct user access to EEPROM (using registers <code>EECONx</code> etc.) is not allowed for security reasons, specialized OS functions are intended for this. • EEPROM area dedicated to OS (locations 0xC0 or higher) is not accessible. See example E04–EEPROM [10].
Side effects	–
See also	<code>eeReadByte</code> , <code>eeWriteByte</code> , <code>eeWriteData</code>
Example 1	<code>eeReadData(10, 16); // copy 16B from EEPROM from address 10 to bufferINFO // bufferINFO[0] = EEPROM[10] // ... // bufferINFO[15] = EEPROM[25]</code>
Example 2	<code>// Illegal access: Avoid access to EEPROM locations 192 (0xC0) or higher eeReadData(200, 16); // EEPROM address 160 is used instead of protected area // bufferINFO[0] = EEPROM[160] // ... // bufferINFO[15] = EEPROM[160]</code>

eeWriteByte

Function	Write one byte to specified location in EEPROM
Purpose	Access to EEPROM
Syntax	<code>void eeWriteByte (addr, data)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 addr</code>: address in EEPROM (0xA0 to 0xBF for Coordinator and 0 to 0xBF for other devices). See EEPROM map [2]. • <code>uns8 data</code>: value to be written (0 to 255)
Return value	–
Output values	–
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Direct user access to EEPROM (using registers <code>EECONx</code> etc.) is not allowed for security reasons, specialized OS functions are intended for this. • EEPROM area dedicated to OS (locations 0xC0 or higher) is not accessible. See example E04–EEPROM [10]. • Any attempt to write to protected area above 0xBF leads to no operation.
Side effects	–
See also	<code>eeReadByte</code> , <code>eeReadData</code> , <code>eeWriteData</code>
Example 1	<pre>eeWriteByte(191, 0x75) // store 0x75 to EEPROM to address 191 eeWriteByte(0x80, X) // copy X to EEPROM to address 0x80</pre>
Example 2	<pre>// Illegal access: Avoid access to EEPROM locations 192 (0xC0) or higher eeWriteByte(198, 0x75); // Attempt to write to protected area - nothing is written.</pre>

eeWriteData

Function	Write a block of specified length from <code>bufferINFO</code> to specified location in EEPROM
Purpose	Block access to EEPROM
Syntax	<code>void eeWriteData (addr, length)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 addr</code>: address in EEPROM . See EEPROM map [2]. <ul style="list-style-type: none"> • (0xA0 to 0xBF - length + 1) for Coordinator • (0 to 0xBF - length + 1) for other devices • <code>uns8 length</code>: number of bytes to be written from <code>bufferINFO</code> (1 to 32)
Return value	–
Output values	–
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Direct user access to EEPROM (using registers <code>EECONx</code> etc.) is not allowed for security reasons, specialized OS functions are intended for this. • EEPROM area dedicated to OS (locations 0xC0 or higher) is not accessible. See example E04–EEPROM [10].
Side effects	• Any attempt to write to protected area above 0xBF leads to no operation.
See also	<code>eeReadByte</code> , <code>eeReadData</code> , <code>eeWriteByte</code>
Example 1	<pre>eeWriteData(10,16); // copy 16B from bufferINFO to EEPROM to address 10 // EEPROM[10] = bufferINFO[0] // // EEPROM[25] = bufferINFO[15]</pre>
Example 2	<pre>// Illegal access: Avoid access to EEPROM locations 192 (0xC0) or higher eeWriteData(200,16); // Attempt to write to protected area - nothing is // written.</pre>

Serial EEPROM

eeeReadData

Function	Read a 16 B data block from specified location in serial EEPROM to <code>bufferINFO</code>
Purpose	Block access to serial EEPROM
Syntax	<code>void eeeReadData (addr)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns16 addr</code>: address in serial EEPROM (0 to 0x7F0). It must be divisible by 16 (0x00, 0x10, ..., 0x7F0).
Return value	–
Output values	<code>bufferINFO[0 to 15]</code>
Preconditions	Do not use for Coordinator in networks utilizing Discovery.
Remarks	Memory range 0 to 0x7FF is accessible.
Side effects	–
See also	<code>eeeWriteData</code>
Example	<pre>eeeReadData(64); // copy 16B from serial EEPROM from address 64 to bufferINFO // bufferINFO[0] = serial EEPROM[64] // ... // bufferINFO[15] = serial EEPROM[79]</pre>

eeeWriteData

Function	Write a 16 B data block from <code>bufferINFO</code> to specified location in EEPROM
Purpose	Block access to serial EEPROM
Syntax	<code>void eeeWriteData (addr)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns16 addr</code>: address in serial EEPROM (0 to 0x7FF). It must be divisible by 16 (0x00, 0x10, ..., 0x7F0).
Return value	Memory range 0 to 0x7FF is accessible.
Output values	–
Preconditions	Do not use for Coordinator in networks utilizing Discovery.
Remarks	–
Side effects	–
See also	<code>eeeReadData</code>
Example	<pre>eeeWriteData(64); // copy 16B from bufferINFO to serial EEPROM from address 64 // EEPROM[64] = bufferINFO[0] // ... // EEPROM[79] = bufferINFO[15]</pre>

RAM
readFromRAM

Function	Read one byte from specified location in RAM
Purpose	Indirect access to RAM registers
Syntax	<code>uns8 readFromRAM(addr)</code>
Parameters	<code>uns16 addr</code> : linear or traditional memory location address
Return value	Value read from specified location
Output values	–
Preconditions	–
Remarks	See example E06–RAM [10].
Side effects	FSR0 register is modified.
See also	<code>writeToRAM</code> , <code>copyMemoryBlock</code> , <code>getINDF0</code> , <code>getINDF1</code>
Example	<pre> for (i=0; i<5; i++) { A = readFromRAM(bufferRF + i); ... } </pre>

writeToRAM

Function	Write one byte to specified location in RAM
Purpose	Indirect access to RAM registers
Syntax	<code>void writeToRAM(addr, value)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns16 addr</code>: traditional or linear memory location address • <code>uns8 value</code>: value to be written
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Avoid writing to RAM areas dedicated to OS and to PIC special function registers otherwise OS can collapse. See RAM map [2].
Remarks	RAM can be accessed either directly (using common C commands like <code>X = Y;</code>) or indirectly. But indirect writing to the <code>INDFx</code> registers is not allowed. Due to security reasons all instructions writing to <code>INDFx</code> are removed during Upload. To avoid unintended behavior, all constructions writing to <code>INDFx</code> (either by the user or by the compiler) should be omitted. Instead of this IQRF OS provides complete support for indirect RAM addressing using extra system functions <code>readFromRAM</code> , <code>writeToRAM</code> and <code>copyMemoryBlock</code> . See example E06–RAM [10].
Side effects	<code>FSR0</code> register is modified.
See also	<code>readFromRAM</code> , <code>copyMemoryBlock</code> , <code>setINDF0</code> , <code>setINDF1</code>
Example 1	<pre>// Not allowed. The compiler uses INDFx in such cases. for (i=0; i<5; i++) bufferRF[i] = i;</pre>
Example 2	<pre>// Correct for (i=0; i<5; i++) writeToRAM(bufferRF + i, i);</pre>

setINDF0

Function	Write a value in the virtual INDF0 register
Purpose	Indirect write to RAM
Syntax	<code>void setINDF0 (value)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 value</code>: value to be written
Return value	–
Output values	Register addressed by the <code>FSR0H</code> and <code>FSR0L</code> is modified
Preconditions	<ul style="list-style-type: none"> • <code>FSR0</code> (the <code>FSR0H</code> and <code>FSR0L</code> register pair) must be set before to define a destination. Traditional as well as linear address can be used. • Avoid writing to RAM areas dedicated to OS and to PIC special function registers otherwise OS can collapse. See RAM map [2].
Remarks	<ul style="list-style-type: none"> • Simple writing to the <code>INDF0</code> virtual register is not allowed. Due to security reasons all instructions using <code>INDF0</code> are removed during Upload. To avoid unintended behavior all constructions using addressing via <code>INDF0</code> (either by the user or by the compiler) should be omitted. Instead of this IQRF OS allows to write to indirectly addressed RAM using extra system function <code>setINDF0</code>. See example E06–RAM [10]. • Another possibility is using the <code>writeToRAM</code> function.
Side effects	–
See also	<code>setINDF1</code> , <code>getINDF0</code> , <code>getINDF1</code> , <code>writeToRAM</code> , <code>copyMemoryBlock</code>
Example	See <code>getINDF0</code> (by analogy with <code>INDF1</code>)

setINDF1

Function	Write a value in the virtual INDF1 register
Purpose	Indirect write to RAM
Syntax	<code>void setINDF1 (value)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 value</code>: value to be written
Return value	–
Output values	Register addressed by the <code>FSR1H</code> and <code>FSR1L</code> is modified
Preconditions	<ul style="list-style-type: none"> • <code>FSR1</code> (the <code>FSR1H</code> and <code>FSR1L</code> register pair) must be set before to define a destination. Traditional as well as linear address can be used. • Avoid writing to RAM areas dedicated to OS and to PIC special function registers otherwise OS can collapse. See RAM map [2].
Remarks	<ul style="list-style-type: none"> • Simple writing to the <code>INDF1</code> virtual register is not allowed. Due to security reasons all instructions using <code>INDF1</code> are removed during Upload. To avoid unintended behavior all constructions using addressing via <code>INDF1</code> (either by the user or by the compiler) should be omitted. Instead of this IQRF OS allows to write to indirectly addressed RAM using extra system function <code>setINDF1</code>. See example E06–RAM [10]. • Another possibility is using the <code>writeToRAM</code> function.
Side effects	–
See also	<code>setINDF0</code> , <code>getINDF0</code> , <code>getINDF1</code> , <code>writeToRAM</code> , <code>copyMemoryBlock</code>
Example	See <code>getINDF0</code>

getINDF0

Function	Read a value in the INDF0 virtual register
Purpose	Indirect read from RAM
Syntax	uns8 <code>getINDF0 ()</code>
Parameters	–
Return value	Value of the register addressed by the FSR0H and FSR0L
Output values	–
Preconditions	<ul style="list-style-type: none"> FSR0 (the FSR0H and FSR0L register pair) must be set before to define a destination. Traditional as well as linear address can be used.
Remarks	<ul style="list-style-type: none"> See example E06–RAM [10]. Additionally, simple reading the INDF0 virtual register is allowed from IQRF OS v3.04. This is even less memory consuming than <code>getINDF0</code>. See Example 2 below. Another possibility is using the <code>readFromRAM</code> function.
Side effects	–
See also	<code>setINDF0</code> , <code>setINDF1</code> , <code>getINDF1</code> , <code>readFromRAM</code> , <code>copyMemoryBlock</code>
Example 1	<pre> // Not allowed FSR0 = ADDR_FROM; FSR1 = ADDR_TO; for(i = 0; i < 16; i++) { X = INDF0; // Allowed from OS v3.04 INDF1 = X; // Illegal writing to INDF1 (see setINDF1) FSR0++; FSR1++; } </pre>
Example 2	<pre> // Allowed from OS v3.04 FSR0 = ADDR_FROM; FSR1 = ADDR_TO; for(i = 0; i < 16; i++) { X = INDF0; // Allowed (and recommended) from OS v3.04 setINDF1(X); FSR0++; FSR1++; } </pre>
Example 3	<pre> // Also correct but more memory consuming FSR0 = ADDR_FROM; FSR1 = ADDR_TO; for(i = 0; i < 16; i++) { X = getINDF0(); setINDF1(X); FSR0++; FSR1++; } // Result is the same as copyMemoryBlock(ADDR_FROM, ADDR_TO, 16) </pre>

getINDF1

Function	Read a value in the INDF1 virtual register
Purpose	Indirect read from RAM
Syntax	uns8 getINDF1 ()
Parameters	–
Return value	Value of the register addressed by the FSR1H and FSR1L
Output values	–
Preconditions	<ul style="list-style-type: none"> FSR1 (the FSR1H and FSR1L register pair) must be set before to define a destination. Traditional as well as linear address can be used.
Remarks	<ul style="list-style-type: none"> See example E06–RAM [10]. Additionally, simple reading the INDF1 virtual register is allowed from IQRF OS v3.04. This is even less memory consuming than getINDF1. See getINDF0, Example 2 . Another possibility is using the readFromRAM function.
Side effects	–
See also	setINDF0, setINDF1, getINDF0, readFromRAM, copyMemoryBlock
Example	See getINDF0 (by analogy with INDF1)

Buffers

All functions for copying buffers (`copyBufferINFO2RF`, `copyBufferINFO2COM`, `copyBufferRF2COM`, `copyBufferRF2INFO`, `copyBufferCOM2RF`, `copyBufferCOM2INFO`) can use **offsets** `memoryOffsetFrom` and `memoryOffsetTo`. Offsets are applied when at least one of them is different from zero only. Then the following principle will take place: `memoryOffsetFrom` specifies relative offset in the From buffer and `memoryOffsetTo` specifies relative offset in the To buffer. It means that data is not read starting from `bufferXX[0]` but from `bufferXX[memoryOffsetFrom]` and is not stored starting from `bufferYY[0]` but from `bufferYY[memoryOffsetTo]`. Just the final part of the `bufferXX` is copied (from `memoryOffsetFrom` up to the end of the `bufferXX` or `bufferYY`, whichever is reached first, further optionally reduced by `memoryLimit`). In addition to this, the `memoryLimit` variable can be used to specify number of bytes to be transferred.

If both `memoryOffsetFrom = 0` and `memoryOffsetTo = 0` complete buffers (optionally reduced by `memoryLimit`) are copied. Offsets and the `memoryLimit` are default disabled (cleared after reset as well as after every buffer copy).

copyBufferINFO2COM

Function	Copy <code>bufferINFO</code> to <code>bufferCOM</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferINFO2COM()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • If <code>memoryOffsetFrom = 0</code>, <code>memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2RF</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example 1	<code>copyBufferINFO2COM();</code>
Example 2	<pre>memoryOffsetFrom = 0; // bufferINFO to be copied memoryOffsetTo = 10; // to bufferCOM starting from bufferCOM[10]. copyBufferINFO2COM; // Just first 54 B is copied (until bufferCOM full).</pre>
Example 3	<pre>memoryOffsetFrom = 0; // bufferINFO to be copied memoryOffsetTo = 10; // to bufferCOM starting from bufferCOM[10]. memoryLimit = 20; copyBufferINFO2COM; // Just first 20 B is copied (due to memoryLimit).</pre>

copyBufferINFO2RF

Function	Copy <code>bufferINFO</code> to <code>bufferRF</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferINFO2RF ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • If <code>memoryOffsetFrom = 0</code>, <code>memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2COM</code> , <code>copyBufferRF2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2RF</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example	<code>copyBufferINFO2RF ();</code>

copyBufferRF2COM

Function	Copy <code>bufferRF</code> to <code>bufferCOM</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferRF2COM ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • If <code>memoryOffsetFrom = 0</code>, <code>memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferINFO2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2RF</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example	<code>copyBufferRF2COM ();</code>

copyBufferRF2INFO

Function	Copy <code>bufferRF</code> to <code>bufferINFO</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferRF2INFO ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • Copying is limited up to first 64 B of <code>bufferRF</code> only. • If <code>memoryOffsetFrom = 0, memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2COM</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2COM</code> , <code>copyBufferCOM2RF</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example	<code>copyBufferRF2INFO () ;</code>

copyBufferCOM2RF

Function	Copy <code>bufferCOM</code> to <code>bufferRF</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferCOM2RF ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • If <code>memoryOffsetFrom = 0, memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2COM</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example	<code>copyBufferCOM2RF () ;</code>

copyBufferCOM2INFO

Function	Copy <code>bufferCOM</code> to <code>bufferINFO</code>
Purpose	Data transfer between buffers
Syntax	<code>void copyBufferCOM2INFO ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	Offsets <code>memoryOffsetFrom</code> and <code>memoryOffsetTo</code> are applied (see above).
Remarks	<ul style="list-style-type: none"> • If <code>memoryOffsetFrom = 0</code>, <code>memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is copied. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2COM</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2RF</code> , <code>copyMemoryBlock</code>
Example	<code>copyBufferCOM2INFO ();</code>

compareBufferINFO2RF

Function	Compare <code>bufferINFO</code> and <code>bufferRF</code> with respect to specified length
Purpose	Buffer comparison
Syntax	<code>bit compareBufferINFO2RF (length)</code>
Parameters	<code>uns8 length</code> : number of bytes to be compared (1 to 64)
Return value	<ul style="list-style-type: none"> • 1 – match • 0 – mismatch
Output values	–
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Comparing is limited up to first 64 B of <code>bufferRF</code> only. • If <code>memoryOffsetFrom = 0</code>, <code>memoryOffsetTo = 0</code> and <code>memoryLimit = 0</code>, complete 64 B is compared. • See example E06 - RAM [10].
Side effects	–
See also	<code>clearBufferINFO</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2INFO</code> , <code>swapBufferINFO</code>
Example	<pre>if (!compareBufferINFO2RF(32)) // Compare 32 B then Error = 1; // Error if mismatch</pre>

swapBufferINFO

Function	Swap <code>bufferINFO</code> and <code>bufferAUX</code>
Purpose	Temporary <code>bufferINFO</code> saving
Syntax	<code>void swapBufferINFO ()</code>
Parameters	–
Return value	–
Output values	Content of <code>bufferINFO</code> and <code>bufferAUX</code> (64 B) is swapped. See example E06 - RAM [10].
Preconditions	–
Remarks	–
Side effects	–
See also	<code>moduleInfo</code> , <code>appInfo</code>
Example	<pre> swapBufferInfo(); // Temporarily save bufferInfo to bufferAUX appInfo(); // Get user data from EEPROM ... swapBufferInfo(); // and restore previous data in bufferInfo </pre>

clearBufferINFO

Function	Clear <code>bufferINFO</code>
Purpose	<code>bufferINFO</code> clearing
Syntax	<code>void clearBufferINFO ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	–
Remarks	Complete <code>bufferINFO</code> (64 B) is cleared (filled with zeros). See example E06 - RAM [10].
Side effects	–
See also	<code>copyBufferINFO2COM</code> , <code>copyBufferINFO2RF</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2INFO</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code> , <code>swapBufferINFO</code>
Example	<code>clearBufferINFO ();</code>

clearBufferRF

Function	Clear <code>bufferRF</code>
Purpose	<code>bufferRF</code> clearing
Syntax	<code>void clearBufferRF ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	–
Remarks	Complete <code>bufferRF</code> (128 B) is cleared (filled with zeros). See example E06 - RAM [10].
Side effects	–
See also	<code>copyBufferRF2COM</code> , <code>copyBufferRF2INFO</code> , <code>copyBufferCOM2RF</code> , <code>copyBufferINFO2RF</code> , <code>compareBufferINFO2RF</code> , <code>copyMemoryBlock</code>
Example	<code>clearBufferRF ();</code>

Data blocks
copyMemoryBlock

Function	Copy specified RAM block to specified location
Purpose	Copy memory block within RAM
Syntax	<code>void copyMemoryBlock (from, to, length)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns16 from</code>: starting address of the block to be copied • <code>uns16 to</code>: destination address • <code>uns8 length</code>: block length in bytes
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Either traditional or linear addresses can be used. • Upward overlapping the source and the destination RAM blocks being copied is not allowed. • Avoid writing to RAM areas dedicated to OS otherwise OS can collapse. See the RAM map [2].
Remarks	<ul style="list-style-type: none"> • See RAM map [2] and example E06 - RAM [10].
Side effects	FSR0 and FSR1 registers are modified.
See also	<code>writeToRAM</code> , <code>readFromRAM</code> , <code>setINDF0</code> , <code>getINDF0</code> , <code>setINDF1</code> , <code>getINDF0</code>
Example 1	<code>copyMemoryBlock(0x2390, 0x23C0, 10); // copy 10 B block from 0x2390 to 0x23C0</code>
Example 2	<code>copyMemoryBlock(bufferRF+10, bufferCOM+1, 8); // 8 bytes copied: // bufferCOM[1] = bufferRF[10] ... bufferCOM[8] = bufferRF[17]</code>
Example 3	<code>copyMemoryBlock(array+0, array+1, sizeof(array)-1); // Upward, not allowed</code>
Example 4	<code>copyMemoryBlock(array+1, array+0, sizeof(array)-1); // Downward, allowed</code>

moduleInfo

Function	Store Module data to <code>bufferINFO</code>																																				
Purpose	Get information about transceiver module and OS																																				
Syntax	<code>void moduleInfo ()</code>																																				
Parameters	–																																				
Return value	–																																				
Output values	<p><code>bufferINFO[0 to 7]</code>:</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 60%;">Address in <code>bufferInfo</code></th> <th style="width: 5%;">7</th> <th style="width: 5%;">6</th> <th style="width: 5%;">5</th> <th style="width: 5%;">4</th> <th style="width: 5%;">3</th> <th style="width: 5%;">2</th> <th style="width: 5%;">1</th> <th style="width: 5%;">0</th> </tr> </thead> <tbody> <tr> <td style="background-color: #e0e0e0;">Meaning</td> <td colspan="2" style="text-align: center;">OS build</td> <td style="text-align: center;">TR type</td> <td style="text-align: center;">OS version</td> <td colspan="4" style="text-align: center;">Serial number Module ID</td> </tr> </tbody> </table> <p>Serial number (Module ID): 4 B identification code unique for each TR module.</p> <p>OS version:</p> <ul style="list-style-type: none"> Upper nibble (4 b): Major version Lower nibble (4 b): Minor version. Postfix "D" is not stated in Module identification but can be recognized by MCU type ("D" for PIC16LF1938). <p>TR type:</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 10%;">Bit</th> <th style="width: 10%;">7</th> <th style="width: 10%;">6</th> <th style="width: 10%;">5</th> <th style="width: 10%;">4</th> <th style="width: 10%;">3</th> <th style="width: 10%;">2</th> <th style="width: 10%;">1</th> <th style="width: 10%;">0</th> </tr> </thead> <tbody> <tr> <td style="background-color: #e0e0e0;">Meaning</td> <td colspan="4" style="text-align: center;">TR series</td> <td colspan="4" style="text-align: center;">MCU type</td> </tr> </tbody> </table> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="width: 45%;"> <p>TR series (from OS v3.05D)</p> <ul style="list-style-type: none"> 0: TR-52D 1: TR-58D-RJ 2: TR-72D 3: TR-53D 8: TR-54D 9: TR-55D 10: TR-56D </div> <div style="width: 45%;"> <p>MCU type</p> <ul style="list-style-type: none"> 3: PIC16F886 4: PIC16LF1938 </div> </div> <p>OS build: OS subversion for the manufacturer only.</p> <p>DCTR identification:</p> <ul style="list-style-type: none"> The most significant bit of Module ID: 0: TR (fully programmable, Demo HWP allowed, General HWP not allowed) 1: DCTR (fully programmable, Demo HWP allowed, General HWP allowed) <p><i>Examples (all in hexadecimal):</i></p> <pre style="font-family: monospace;"> [0] [1] [2] [3] [4] [5] [6] [7] bufferINFO[0-7] = 1C 10 00 01 35 A4 39 11 </pre> <p>Meaning: Module ID = 0100101C, TR, IQRF OS version 3.05D, TR-56D, PIC16LF1938, build 0x1139.</p> <pre style="font-family: monospace;"> [0] [1] [2] [3] [4] [5] [6] [7] bufferINFO[0-7] = 1C 10 00 81 35 A4 39 11 </pre> <p>Meaning: Module ID = 8100101C, DCTR, IQRF OS version 3.05D, TR-56D, PIC16LF1938, build 0x1139.</p>	Address in <code>bufferInfo</code>	7	6	5	4	3	2	1	0	Meaning	OS build		TR type	OS version	Serial number Module ID				Bit	7	6	5	4	3	2	1	0	Meaning	TR series				MCU type			
Address in <code>bufferInfo</code>	7	6	5	4	3	2	1	0																													
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Bit	7	6	5	4	3	2	1	0																													
Meaning	TR series				MCU type																																
Preconditions	–																																				
Remarks	Module data can also be read by SPI master. See the IQRF SPI specification [5].																																				
Side effects	<code>bufferINFO[8 to 63]</code> is modified.																																				
See also	<code>appInfo</code>																																				

Example 1	<pre> uns24 SN @ bufferInfo; uns8 OSv @ bufferInfo[4]; moduleInfo(); // Now SN == module serial number // and OSv == OS version </pre>
Example 2	<pre> moduleInfo(); if (bufferInfo[5].7 == 0) ... // MCU pins are multiplexed (e.g. RC5 and RC7 to TR pin C8 etc.) else ... // MCU pins are not multiplexed (e.g. RC5 and RC7 to TR pin C8 etc.) // See simplified circuit diagram in TR datasheets </pre>

appInfo

Function	Store Application information from EEPROM to <code>bufferINFO</code>
Purpose	Get information about user application
Syntax	<code>void appInfo ()</code>
Parameters	–
Return value	–
Output values	<code>bufferINFO[0 to 31]</code>
Preconditions	–
Remarks	See IQRF OS User's guide [1] (Identification and Appendix, Memory maps).
Side effects	–
See also	<code>moduleInfo</code>
Example 1	<pre> appInfo(); // Copy Application info from EEPROM to bufferINFO copyBufferINFO2RF(); // and then to bufferRF </pre>
Example 2	<pre> #pragma packedCdataStrings 0 // Application data to EEPROM after compilation #pragma cdata[__EEAPPINFO] = "Application data, I'm user #01 " bufferINFO[0] = '2'; // Dynamic change of application data eeWriteData(__EEAPPINFO+29,1); // #01 changed to #02 appInfo(); // "Application data, I'm user #02 " is read </pre>

SPI
enableSPI

Function	Activate SPI communication module and related pins
Purpose	Enable SPI communication
Syntax	<code>void enableSPI ()</code>
Parameters	–
Return value	–
Output values	SPI Status is switched to <i>SPI ready, communication mode</i> .
Preconditions	–
Remarks	<ul style="list-style-type: none"> • The PIC internal SPI hardware module and appropriate pins (C5 to C8 or Q6, Q7, Q8 and Q11) are configured and activated as SPI Slave. • See SPI Implementation in IQRF TR modules [5] and example E07-SPI [10].
Side effects	Related pins can not be used as general I/Os until SPI is disabled via <code>disableSPI</code> .
See also	<code>disableSPI</code> , <code>startSPI</code> , <code>stopSPI</code> , <code>getStatusSPI</code> , <code>restartSPI</code>
Example	See <code>getStatusSPI</code>

disableSPI

Function	Switch SPI HW module off and configure SPI pins as I/Os
Purpose	Disable SPI communication
Syntax	<code>void disableSPI ()</code>
Parameters	–
Return value	–
Output values	SPI Status is switched to <i>SPI not active</i> .
Preconditions	–
Remarks	The PIC internal SPI hardware module is disabled and related pins (C5 to C8 or Q6, Q7, Q8 and Q11) are reconfigured as general I/Os. See SPI Implementation in IQRF TR modules [5] and example E07-SPI [10].
Side effects	<ul style="list-style-type: none"> • The appropriate PIC pins are not restored to the state before <code>enableSPI</code> calling. • Current packet is lost by both sides if SPI communication is running on background at this moment.
See also	<code>enableSPI</code> , <code>startSPI</code> , <code>stopSPI</code> , <code>getStatusSPI</code> , <code>restartSPI</code>
Example	See <code>getStatusSPI</code>

startSPI

Function	Indicate ready to Master.
Purpose	<ul style="list-style-type: none"> Initiate SPI packet transmission from Slave (request to Master). Provide data from <code>bufferCOM</code> to Master according to Master's clock (on OS background). <code>startSPI(0)</code> indicates to Master that the Slave is ready to receive data (<code>bufferCOM</code> not full).
Syntax	<code>void startSPI (length)</code>
Parameters	<code>uns8 length</code> : number of bytes to be sent (0 to 64)
Return value	–
Output values	SPI Status is switched to: <ul style="list-style-type: none"> <i>SPI data ready</i> – after <code>startSPI(1 to 64)</code> <i>SPI ready, Communication mode</i> – after <code>startSPI(0)</code>.
Preconditions	<ul style="list-style-type: none"> SPI must be enabled by the <code>enableSPI</code> function before. <code>startSPI</code> must not be combined with functions changing <code>bufferCOM</code>, e.g. <code>discovery</code> and <code>responseFRC</code>.
Remarks	<ul style="list-style-type: none"> SPI runs on OS background. <code>startSPI(0)</code> is also useful for recovering SPI from communication failures (e.g. the CRC mismatch). See SPI Implementation in IQRF TR modules [5] and example E07-SPI [10].
Side effects	–
See also	<code>enableSPI</code> , <code>disableSPI</code> , <code>stopSPI</code> , <code>getStatusSPI</code> , <code>restartSPI</code>
Example 1	<pre> // Slave -> Master bufferCOM[0] = "I"; bufferCOM[1] = "Q"; enableSPI(); startSPI(2); // Request to Master is active on background from now ... // and the program just continues here </pre>
Example 2	<code>startSPI(0);</code> // Reset SPI communication
Example 3	See <code>getStatusSPI</code>

stopSPI

Function	Stop SPI communication
Purpose	Suspend SPI transmissions whenever it suits to Slave
Syntax	<code>void stopSPI ()</code>
Parameters	–
Return value	–
Output values	SPI Status is switched to <i>User stop</i> .
Preconditions	–
Remarks	<ul style="list-style-type: none"> • <code>stopSPI</code> is useful e.g. to avoid violation during preparation data to <code>bufferCOM</code>. • SPI transmission is stopped but SPI remains active (enabled). Communication can continue after next <code>startSPI</code>. • <code>stopSPI</code> is not needed after successful SPI reception to protect data received in <code>bufferCOM</code>. Data is protected by OS (and SPI status stays in mode 3F) until the slave allows further communication e.g. by the <code>startSPI (0)</code>. • <code>startSPI</code> and <code>stopSPI</code> are not fully complementary. Receiving is allowed just after <code>enableSPI</code> without previous <code>startSPI</code>, <code>startSPI</code> is meaningful after previous <code>startSPI</code> not followed by <code>stopSPI</code> etc. • See SPI Implementation in the IQRF TR modules [5] and example E07-SPI [10].
Side effects	Current packet is lost by both sides if SPI communication is running on background at this moment.
See also	<code>enableSPI</code> , <code>disableSPI</code> , <code>startSPI</code> , <code>getStatusSPI</code> , <code>restartSPI</code>
Example	<pre> if (!getStatusSPI()) // If SPI is not in progress { stopSPI(); // Prohibit Master from transmitting // (not to destroy bufferCOM in background) bufferCOM[0] = ... // Prepare data to send bufferCOM[1] = ... startSPI(2); // Request to send } </pre>

restartSPI

Function	Indicate ready to continue SPI transfer to Master .
Purpose	Allow to continue SPI transmission (request to Master).
Syntax	<code>void restartSPI ()</code>
Parameters	–
Return value	–
Output values	
Preconditions	Intended after preceding <code>stopSPI</code> .
Remarks	SPI can continue from the state just before <code>stopSPI</code> .
Side effects	–
See also	<code>startSPI</code> , <code>stopSPI</code>
Example	<pre> startSPI(16); // SPI started ... stopSPI(); // SPI stopped temporarily ... // to make some operations restartSPI(); // and allow to continue </pre>

getStatusSPI

Function	Update SPI flags and packet length and check whether SPI is busy
Purpose	Provide application program with information about current SPI status
Syntax	bit <code>getStatusSPI ()</code>
Parameters	–
Return value	<ul style="list-style-type: none"> • 1 – SPI busy • 0 – SPI not busy
Output values	<ul style="list-style-type: none"> • SPIpacketLength: received packet length • param2.3 (_SPIRX): 1 – Something received on SPI. • param2.4 (_SPICRCok): 1 – The last received SPI CRCM was O.K.
Preconditions	SPI must be enabled by <code>enableSPI</code>
Remarks	<ul style="list-style-type: none"> • Output values (param2) has different format than SPI status sent to the Master. • See SPI Implementation in IQRF TR modules [5] and example E07-SPI [10].
Side effects	–
See also	<code>enableSPI</code> , <code>disableSPI</code> , <code>startSPI</code> , <code>stopSPI</code> , <code>restartSPI</code>
Example 1	<pre> // Master -> Slave enableSPI(); // Master is allowed to transmit from now Receive: clrwdt(); if (getStatusSPI()) // Wait until SPI is not busy goto Receive; if (_SPIRX) // Anything received? { // Yes: if (!_SPICRCok) // CRCM matched? { // No: startSPI(0); // Restart SPI goto Receive; // and try to receive again. } // Yes: // BufferCOM is automatically protected now // not to be overwritten by next SPI packet. // Thus, stopSPI is not necessary here. // Packet length is in SPIpacketLength. copyBufferCOM2INFO(); // Store received packet startSPI(0); // and then allow Master to transmit again. } else goto Receive; // Nothing received yet // ... Continue here after successful receiving waitMS(1); // Time for finishing startSPI(0) on background disableSPI(); // otherwise Master's CRCS check fails. // The delay depends on Master application. </pre>
Example 2	<pre> enableSPI(); startSPI(2); // 2 B to send to master while (getStatusSPI()) // Wait until SPI is not busy waitMS(1); ... // Now the transfer is finished </pre>

RF
setTXpower

Function	Set RF output power
Purpose	Change RF range
Syntax	<code>void setTXpower (level)</code>
Parameters	uns8 level: 0 (min.) to 7 (max. – default) See datasheet of TR module, Table 2.
Return value	–
Output values	Available read only in the RFpower register
Preconditions	–
Remarks	–
Side effects	–
See also	RFTXpacket
Example	<code>setTXpower(7); // Max. RF output power</code>

setRFspeed

Function	Select RF bit rate
Purpose	Select RF bit rate
Syntax	<code>void setRFspeed (speed)</code>
Parameters	uns8 speed: <ul style="list-style-type: none"> • 1 1.2 kb/s (preliminary, not for 433 MHz TR modules) • 2 19.2 kb/s (default) • 3 57.6 kb/s (preliminary, not for 433 MHz TR modules) • 4 86.2 kb/s (preliminary, not for 433 MHz TR modules)
Return value	–
Output values	Available read only in the RFspeed register
Preconditions	Bit rates different from 19.2 kb/s are preliminary, for experimental purpose only.
Remarks	<ul style="list-style-type: none"> • Non-default bit rates are provisionally intended for experimental purposes only. • Routing is supported for 19.2 kb/s only
Side effects	RF channel must be specified after every bit rate change.
See also	setRFchannel
Example 1	<code>setRFspeed(1); // 1.2 kb/s selected</code> <code>setRFchannel(...); // channel must be selected then</code>
Example 2	<code>setRFspeed(2); // 19.2 kb/s selected</code> <code>setRFchannel(...); // channel must be selected then</code>

setRFband

Function	Select RF frequency band
Purpose	Select 868 MHz or 916 MHz band
Syntax	<code>void setRFband (band)</code>
Parameters	uns8 band: <ul style="list-style-type: none"> • 0 868 band MHz (default) • 1 916 band MHz
Return value	–
Output values	Flag <code>_916MHz</code> in the <code>userInterface</code> register: <code>_916MHz</code> : 0 – 868 MHz band 1 – 916 MHz band
Preconditions	<ul style="list-style-type: none"> • This function is not implemented for TR modules with fixed band, e.g. TR-54D-433. • To ensure compatibility with future OS versions, it is not recommended to use this function from OS v3.04D. RF band should be configured in IQRF IDE (<i>TR Configuration</i>).
Remarks	Default RF band and channel after reset are set according to <i>TR Configuration</i> .
Side effects	RF channel must be specified after every band change.
See also	<code>setRFchannel</code>
Example1	<code>setRFband(1); // 916 MHz band selected</code>
Example2	<code>setRFband(0); // 868 MHz band selected</code>

setRFchannel

Function	Set RF channel
Purpose	Select free RF channel for not interfered communication
Syntax	<code>void setRFchannel (channel)</code>
Parameters	<ul style="list-style-type: none"> • <code>uns8 channel</code>: see IQRF OS User's guide, Appendix 2, Channel map • Default: <ul style="list-style-type: none"> • 868 MHz band: 52 • 916 MHz band: 104 • 433 MHz band: 8 Default channel can be changed by <i>TR Configuration</i> in IQRF IDE.
Return value	–
Output values	Available read only in the <code>RFchannel</code> register
Preconditions	–
Remarks	Channel 0 is reserved for DPA service purposes. It is not recommended to use it for regular communication.
Side effects	RF channel must be specified after every bit rate change.
See also	<code>setRFspeed</code>
Example	<code>setRFspeed(3); // 57.6 kb/s bit rate selected</code> <code>setRFchannel(25); // 868.15 MHz channel selected</code>

setRFmode

Function	Set RF mode
Purpose	Specify RFRX and RFTX power modes, signal filtering modes for RFRX and enable fast response to external signal during LP/XLP RFRX.
Syntax	<code>void setRFmode (mode)</code>
Parameters	<p>uns8 mode: SWTTFFRR in binary</p> <ul style="list-style-type: none"> • S: Stay in RX mode (for fast response for following <code>checkRF</code>, <code>RFRXpacket</code> or <code>RFTXpacket</code>) <ul style="list-style-type: none"> 1 RX chain stays enabled after <code>checkRF</code>, <code>RFRXpacket</code> and <code>RFTXpacket</code> 0 RX chain is disabled after <code>checkRF</code>, <code>RFRXpacket</code> and <code>RFTXpacket</code> • W: Wait packet end <ul style="list-style-type: none"> 1 Waits until receipt is finished if data payload (but not the preamble) is currently receiving, even though <code>toutRF</code> timeout is over meanwhile. 0 <code>RFRXpacket</code> is unconditionally finished when <code>toutRF</code> timeout is over. • TT: TX mode <ul style="list-style-type: none"> 00 for STD RX mode (standard preamble ~3 ms) 01 for LP RX mode (prolonged preamble ~50 ms) 10 for XLP RX mode (prolonged preamble ~900 ms) 11 LP/XLP RX asynchronous termination on pin change enabled. If enabled and no packet is just received, low level on pin C5 (for TR modules in SIM format) or Q12 (for TR-54D) terminates RF reception in LP/XLP mode, immediately or after current cycle finishing. See examples 3 and 4. • FF: Filter incoming signal in LP, XLP and RFIM RX modes (<code>RR</code> ≠ 0). Signal with lower level is ignored. Relative RF range is shortened due to this filtration. The level corresponds to the <code>checkRF(x)</code> parameter: <ul style="list-style-type: none"> 00 x = 5 01 x = 20 10 x = 35 11 x = 50 • RR: RX mode <ul style="list-style-type: none"> 00 STD RX mode (Standard, transmitting device should have <code>TT=00</code>) 01 LP RX mode (Low power, transmitting device should have <code>TT=01</code>) 10 XLP RX mode (Extra low power, transmitting device should have <code>TT=10</code>) 11 RFIM mode (<code>RFRXpacket</code> is terminated when signal strength falls below the FF level)
Return value	–
Output values	Available read only in the <code>RFmodeByte</code> register.
Preconditions	<ul style="list-style-type: none"> • Default value is mode = 0. • Non-STD RX modes are intended for bit rate 19.2 kb/s only.
Remarks	<i>Tip:</i> As the parameters, use constants (and their ored combinations), especially the predefined ones in <code>IQRF-macros.h</code> header file instead of binary values. See example E10-RFMODE and Example 1 below.
Side effects	RF circuitry and MCU is temporarily set to sleep during low power RX modes. Thus, all tasks running on OS background (e.g. SPI communication, LED indication etc.) can be untimely canceled. To avoid this, use <code>setRFmode</code> after finishing all background tasks. See Example 2.
See also	<code>checkRF</code>
Example 1	<pre> // RX: STD, no filtering, TX: for STD RX (standard preambles) setRFmode(0b00000000); // Using numeral value setRFmode(_RX_STD _TX_STD) // The same using predefined constants for clarity // RX: LP, lowest filtering (5), TX: for LP RX (prolonged preambles ~50 ms) setRFmode(0b00010001); // Using numeral value setRFmode(_RX_LP _TX_LP) // The same using predefined constants for clarity </pre>

Example 2	<pre> while (getStatusSPI()) // Wait for finishing SPI on background clrwdt(); disableSPI(); SWDTEN = 0; // Possibly disable WDT for lower consumption setRFmode(_RX_LP _TX_LP); // and go to LP mode then </pre>
Example 3	<pre> // RFRXpacket terminated after low level on C5/Q12 is detected and // current cycle is finished. toutRF = 100; // [in cycles], 1 cycle == ~770 ms while (1) { setRFmode(_RX_XLP _RLPMAT); // RX_XLP + LP/XLP RX termination if (RFRXpacket()) { ... } ... // Goes here after every 77 s (toutRF=100) or // if low level appears on the C5/Q12 pin // in a moment when RX XLP cycle is finished if (buttonPressed) { ... setRFmode(_RX_STD); // Set required TX preamble RFTXpacket(); } } </pre>
Example 4	<pre> // RFRXpacket terminated immediately after low level on C5/Q12 is detected. // It is necessary to activate interrupt on change periodically. toutRF = 100; // [in cycles], 1 cycle == ~770 ms while (1) { setRFmode(_RX_XLP _RLPMAT); // RX_XLP + LP/XLP RX termination writeToRAM(&IOCBN, IOCBN 0x10); // Negative edge active. // Instead of IOCBN.4=1; // Bit IOCBN.4 cannot be accessed // directly due to OS restriction. IOCBP.4 = 1; // Positive edge active too IOCFIE = 1; // Interrupt on change enabled writeToRAM(&IOCBF, IOCBF & 0xEF); // Clear interrupt on change flag. // Instead of IOCBF.4=0; // Bit IOCBF.4 cannot be accessed // directly due to OS restriction. if (RFRXpacket()) { ... } ... // Goes here after every 77 s (toutRF=100) or // immediately if low level appears on the C5/Q12 pin if (buttonPressed) { ... setRFmode(_RX_STD); // Set required TX preamble RFTXpacket(); } } </pre>

checkRF

Function	Check incoming RF signal strength for specified level.
Purpose	Incoming RF signal detection to start RF receiving.
Syntax	<code>bit checkRF(level)</code>
Parameters	<p><code>uns8 level = DQI + RSSI_FILTER</code></p> <ul style="list-style-type: none"> DQI (Data Quality Indicator): <ul style="list-style-type: none"> <code>0x80</code> DQI enabled <code>0</code> DQI disabled <p>If DQI is enabled <code>checkRF</code> returns true when there is an extended probability that just the FSK modulation is detected. See the RF IC datasheet. This can help to distinguish noise from valid signal.</p> <ul style="list-style-type: none"> RSSI_FILTER: 0 to 64 <p>Higher level requires stronger signal. Relative RF range is shortened due to this filtration according the datasheet of the TR module, Table 3. RSSI offset is 32, e.g. level 16 means a signal with RSSI > 48.</p>
Return value	<ul style="list-style-type: none"> 0: Signal with specified level or higher not detected RSSI < RSSI_FILTER, with respect to possible DQI 1: Signal with specified level or higher detected RSSI > RSSI_FILTER, with respect to possible DQI
Output values	<ul style="list-style-type: none"> Signal strength is also available as a relative value in the ADRESH (one of PIC SFR registers). Higher value means stronger signal. If 1 is returned the RF IC stays in RX mode (RX chain on)
Preconditions	<ul style="list-style-type: none"> This function is intended for STD and RFIM receive modes but not for LP and XLP. If DQI enabled <code>PORTA.6 = 1</code> must be set before every <code>checkRF</code> usage. See Example 4.
Remarks	<ul style="list-style-type: none"> Higher level means lower sensitivity which requires stronger signal resulting in higher immunity against interferences but allows lower range – see TR datasheet, table Relative RF range vs. level. Checking takes: <ul style="list-style-type: none"> ~950 μs (without RF signal) or ~800 μs (with RF signal) if RX chain is off (bit S = 0 in <code>setRFmode</code>) ~400 μs (with or without RF signal) if RX chain is on (bit S = 1 in <code>setRFmode</code>) Checking consumes ~9.5 mA. This function is intended for fast response and power consumption reduction in STD RX mode. If RF IC is in sleep (after <code>reset</code>, <code>setRFsleep</code> or <code>iqrfSleep</code>), the first <code>checkRF</code> call wakes-up the RF IC but return and output values are not correct. For proper values <code>setRFready</code> should be called first. See examples 5 a 6.
Side effects	A/D converter control registers are changed
See also	<code>setRFmode</code> , <code>RFRXpacket</code> , <code>getRSSI</code> , <code>setRFready</code> , macro <code>setRFRXchain</code> in <code>IQRF-macros.h</code>
Example 1	<pre> // Fast response receiving in STD mode if (checkRF(5)) // Detect signal with RSSI > 37 { if (RFRXpacket()) // Duration according to toutRF only if packet is sent. { // toutRF can be optimized for expected packet length. ... } } // Otherwise only ~1 ms is spent. ... time-critical section can be placed here </pre>
Example 2	<pre> if (checkRF(10)) // Detect signal with RSSI > 42 ... </pre>
Example 3	<pre> // RF signal strength analyzer SWDTEN = 0; // disable watchdog while (1) if (checkRF(3)) pulseLEDR(); // LED flash if signal level >= 3 detected </pre>
Example 4	<pre> PORTA.6 = 1; // Necessary if using DQI if (checkRF(0x85)) // Detect signal with RSSI > 37 using DQI ... </pre>

Example 5	<pre>iqrfSleep(); setRFready(); // RF IC wake-up for follow-up checkRF if (checkRF(5)) pulseLEDG(); else pulseLEDR();</pre>
Example 6	<pre>setRFmode(_STAYRX); ... iqrfSleep(); setRFready(); // RF IC wake-up for follow-up checkRF setRFRXchain(); // Necessary. See IQRF-macros.h if (checkRF(5)) pulseLEDG(); else pulseLEDR();</pre>

getRSSI

Function	Get RSSI (received signal strength indication) value of incoming RF signal.
Purpose	Fast RF signal level detection
Syntax	uns8 <code>getRSSI ()</code>
Parameters	–
Return value	RSSI value. See the RF IC datasheet. Unlike <code>checkRF</code> , no offset is considered.
Output values	–
Preconditions	RF IC must be in RX Receiving mode (RX chain set on). See examples below.
Remarks	<ul style="list-style-type: none"> • Takes 66 μs. • RSSI value is also available in <code>lastRSSI</code> register after successful receipt by <code>RFRXpacket</code>.
Side effects	–
See also	<code>checkRF</code> , <code>RFRXpacket</code>
Example 1	<pre> // With setRFready setRFready(); // Not obligatory. However, the waitMS delay (see // below) must be adjusted with respect to this. setRFmode(_STAYRX); // RX chain will stay on after follow-up checkRF checkRF(0); // Another function to switch RX chain on // (e.g. RFRXpacket) can also be used. Parameter value // is meaningless here. waitMS(1); // Wait until RX chain is on. It depends on // setRFready usage, see Example 2. i = getRSSI(); </pre>
Example 2	<pre> // Without setRFready setRFmode(_STAYRX); // RX chain will stay on after follow-up checkRF checkRF(0); // Another function to switch RX chain on // (e.g. RFRXpacket) can also be used. Parameter value // is meaningless here. waitMS(3); // Wait until RX chain is on. It depends on // setRFready usage, see Example 1. i = getRSSI(); </pre>
Example 3	<pre> // Fast three-channel RF scanner uns8 ch1_rssi, ch2_rssi, ch3_rssi; setRFmode(_STAYRX); // RX chain will stay on after follow-up checkRF checkRF(0); // To switch RX chain on waitMS(3); // Wait until RX chain is on setRFchannel(1); ch1_rssi = getRSSI(); setRFchannel(2); ch2_rssi = getRSSI(); setRFchannel(3); ch3_rssi = getRSSI(); </pre>

RFTXpacket

Function	Send RF packet of specified length from <code>bufferRF</code> .
Purpose	RF transmission
Syntax	<code>void RFTXpacket ()</code>
Parameters	–
Return value	–
Output values	–
Preconditions	<ul style="list-style-type: none"> • Peer-to-peer topology: <ul style="list-style-type: none"> • PIN = 0 (Peer-to-peer) • DLEN = packet length in bytes (0 to 64) • Prepare data to send in <code>bufferRF[0]</code> to <code>bufferRF[DLEN - 1]</code> (if <code>DLEN ≠ 0</code>) • Set RF output power via <code>setTXpower</code> • IQMESH: <ul style="list-style-type: none"> • PIN = 0x80 (IQMESH) • Other network related parameters should also be specified See IQRF OS User's guide [1] and IQMESH specification [4].
Remarks	<ul style="list-style-type: none"> • Unlike SPI, RF communication does not run on OS background. This function is active on foreground until the packet is sent. • Duration depends on TR type, routing algorithm, packet length and timeslot. • See examples E01–TX, E03–TR, E09–LINK [10] and E11–IQMESH-C [10].
Side effects	<ul style="list-style-type: none"> • <code>bufferRF[DLEN]</code> and <code>bufferRF[DLEN+1]</code> are destroyed • System tick timing is slightly affected. • The RF circuitry wakes up (in case of sleeping).
See also	<code>RFRXpacket</code> , <code>setTXpower</code> , <code>setRFmode</code> and (in case of IQMESH) also other RF functions

Example 1	<pre> // Peer-to-peer topology PIN=0; // Peer-to-peer (update also after every RFRXpacket // before every RFTXpacket) setNonetMode(); bufferRF[0] = "I"; // Data to send bufferRF[1] = "Q"; DLEN = 2; // 2 B packet RFTXpacket(); // Send the packet to all Peer-to-peer Nodes in range // and to all IQMESH Nodes having set filtering off // Program stays here until the packet is sent ... // and then continues </pre>
Example 2	<pre> // IQMESH without routing, packet from Coordinator to Node #10 PIN = 0; // PIN preclearing (update also after every RFRXpacket // before every RFTXpacket) setCoordinatorMode(); // The NTWF flag (PIN.7) is set here. bufferRF[0] = "I"; // Data to send bufferRF[1] = "Q"; DLEN = 2; // 2 B packet RX = 10; // Packet for Node #10 // _ROUTEF = 0; // Routing disabled - not necessary (default by OS) RFTXpacket(); // Send the packet to IQMESH Node #10 in this network // Reception depends on the Node (its current network // or filtering) </pre>
Example 3	<pre> // IQMESH with routing // Packet from Coordinator to Node #10 PIN = 0; // PIN preclearing (update also after every RFRXpacket // before every RFTXpacket) setCoordinatorMode(); // The NTWF flag (PIN.7) is set here. bufferRF[0] = "I"; // Data to send bufferRF[1] = "Q"; DLEN = 5; // 5 B packet RX = 10; // Packet for Node #10 _ROUTEF = 1; // Routing enabled for outgoing packets RTDEF = 1; // SFM (Static Full MESH) // RTDEF = 2; // DFM (Discovered Full MESH) RTHOPS = 10; // 10 hops // RTHOPS = eeReadByte[0]; // # hops = # bonded nodes RTTSLOT = 2; // Time slot = 2 ticks (20 ms is enough for DLEN=5) RFTXpacket(); // Send the packet to IQMESH Node #10 in this network // Reception depends on the Node (its current network // or filtering) </pre>

RFRXpacket

Function	Receive RF packet to <code>bufferRF</code> and provide related information
Purpose	RF receiving
Syntax	bit <code>RFRXpacket ()</code>
Parameters	–
Return value	<ul style="list-style-type: none"> • 1 – packet received • 0 – packet not received
Output values	<ul style="list-style-type: none"> • <code>lastRSSI</code> – the RSSI value after successful receipt (single sample). Quiet level (noise) is 25 - 28. • <code>DLEN</code> = packet length. This variable is destroyed if the receipt is not successful. • <code>PIN</code> is updated according to packet received. This variable is destroyed if the receipt is not successful. • <code>_NTWPACKET</code>: valid if <code>RFRXpacket</code> return value == 1 only: <ul style="list-style-type: none"> • 1 – networking packet received • 0 – non-networking packet received • Other related networking information in case of IQMESH.
Preconditions	<ul style="list-style-type: none"> • Timeout should be specified in <code>toutRF</code> (1 to 255) in number of 10 ms ticks or for LP and XLP modes in cycles, see IQRF OS User's guide, RF RX and TX modes). • Peer-to-peer topology: nothing else • IQMESH: network related parameters (filtering, ...) should be predefined See IQRF OS User's guide [1] and IQMESH specification [4].
Remarks	<ul style="list-style-type: none"> • Unlike SPI, RF communication does not run on OS background. This function is active on foreground until the packet is received or timeout expired. Timeout during packet receiving terminates the reception except of the Wait packet end mode – see <code>setRFmode</code>. • If the packet is sent when the addresse (or a routing device) is not executing this function the packet is lost. • Peer-to-peer topology: All non-networking packets in range are received. • IQMESH: Device receives only packets intended for it and non-networking packets depending on filtering mode – see <code>setNetworkFilteringOn</code> and <code>setNetworkFilteringOff</code>. • <code>RFRXpacket</code> is abandoned cca 105 ms (in LP mode) or cca 1005 ms (in XLP mode) after the packet transmission start. • After termination in LP mode, RF IC is switched to RF ready mode. • After termination in XLP mode, RF IC is switched to RF sleep mode. • <code>RFRXpacket</code> is allowed to be called at least 5 ms after <code>RFTXpacket</code> in LP and XLP modes. See Example 4. • See examples E02–RX, E03–TR, E09–LINK, E11-IQMESH-N and E14-CONSUMPTION [10].
Side effects	<ul style="list-style-type: none"> • Update <code>PIN</code> before every <code>RFTXpacket</code> followed after <code>RFRXpacket</code>. • Result of <code>captureTicks</code> is destroyed if <code>startCapture</code> is active on background at the same time. • System tick timing is slightly affected. • <code>bufferRF[DLEN]</code> and <code>bufferRF[DLEN+1]</code> is destroyed. • The RF circuitry wakes up (in case of sleeping). • If a packet received the A/D converter control registers are changed.
See also	<code>RFTXpacket</code> , <code>setRFmode</code> , <code>checkRF</code> and (in case of IQMESH) also other RF functions

Example 1	<pre> // Peer-to-peer topology toutRF = 10; // RF timeout 100 ms if (RFRXpacket()) // Try to receive RF packet. // Program stays here until the packet is received // or the timeout is expired. Packet received? { copyBufferRF2INFO(); // Store received data PacketLength = DLEN; // and possibly other info (packet length, ...) } else { // No: ... // Timeout expired. Arrange respective operations. } </pre>
Example 2	IQMESH: See setNodeMode and setNetworkFilteringOn.
Example 3	<pre> if (RFRXpacket()) { if (_ROUTEF) // Was the packet routed? { // Yes - wait for finish of routing while (RTHOPS) // RTHOPS - rest of hops { waitDelay(RTTSLOT); // RTTSLOT - timeslot RTHOPS--; // Do not answer until all hops are finished } } ... // Now the Node is allowed to answer } </pre>
Example 4	<pre> setRFmode(_RX_LP); // or _RX_XLP ... RFTXpacket(); ... // If there is no other code taking at least 5 ms, waitMS(5); // the delay must be included here if (RFRXpacket()) ... </pre>

Networking

setCoordinatorMode

Function	Set Coordinator mode
Purpose	Assign the TR module as a network Coordinator
Syntax	<code>void setCoordinatorMode ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • Flag <code>_networkingMode (userInterface.7) = 1</code> • Flag <code>_networkTwo (userInterface.6) = 0</code> • In Coordinator mode the <code>_NTWF</code> flag (PIN.7) is automatically set before calling <code>RFTXpacket</code>
Preconditions	For IQMESH only
Remarks	Every TR module can work as a Coordinator or a Node. Just one Coordinator in single network is allowed. Avoid dynamic switching the Coordinator from device to device in a network. This settings affects both <code>RFRXpacket</code> and <code>RFTXpacket</code> .
Side effects	–
See also	<code>setNodeMode</code> , <code>setNonetMode</code> , <code>RFTXpacket</code>
Example	

setNodeMode

Function	Set Node mode
Purpose	Assign the TR module as a network Node
Syntax	<code>void setNodeMode ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • Flag <code>_networkingMode (userInterface.7) = 1</code> • Flag <code>_networkTwo (userInterface.6) = 1</code> • In Node mode the <code>_NTWF</code> flag (PIN.7) is automatically set before calling <code>RFTXpacket</code>
Preconditions	For IQMESH only
Remarks	Every TR module can work as a Coordinator or a Node. This settings affects both <code>RFRXpacket</code> and <code>RFTXpacket</code> .
Side effects	–
See also	<code>setCoordinatorMode</code> , <code>setNonetMode</code> , <code>RFTXpacket</code>
Example	

setNonetMode

Function	Select Peer-to-peer mode
Purpose	Switch from IQMESH to Peer-to-peer
Syntax	void setNonetMode ()
Parameters	–
Return value	–
Output values	• Flag <code>_networkingMode</code> (<code>userInterface.7</code>) = 0
Preconditions	–
Remarks	<ul style="list-style-type: none"> • Default OS mode is Peer-to-peer. • This settings affects <code>RFRXpacket</code> and <code>RFTXpacket</code> features. • PIN is not affected immediately but it is cleared after subsequent <code>RFRXpacket</code> or <code>RFTXpacket</code>. • Flag <code>_networkTwo</code> (<code>userInterface.6</code>) is not changed.
Side effects	–
See also	<code>setCoordinatorMode</code> , <code>setNodeMode</code>
Example	<pre> setNetworkOne(); // TR communicates in IQMESH networking mode here ... // setNonetMode(); // Switch to Peer-to-peer mode ... // Now TR communicates without networking support </pre>

setNetworkFilteringOn

Function	Start filtering incoming non-networking packets and packets coming from non-current network.
Purpose	To receive packets from current network only.
Syntax	void setNetworkFilteringOn ()
Parameters	–
Return value	–
Output values	Flag <code>_filterCurrentNetwork</code> in register <code>userInterface</code> : <code>_filterCurrentNetwork</code> : 0 - filtering off 1 - filtering on • This affects the <code>RFRXpacket</code> return value.
Preconditions	For IQMESH only. Default OS condition is Filtering Off.
Remarks	–
Side effects	–
See also	<code>setNetworkFilteringOff</code> , <code>RFRXpacket</code>
Example	<pre> setNetworkFilteringOn(); // Start filtering incoming packets RFRXpacket(); // Return value == 1 if the packet came // from current network only. // Return value == 0 if // the packet came from non-current network(s) // or it is a non-networking packet // or no packet came in time at all. </pre>

setNetworkFilteringOff

Function	Stop filtering incoming packets from the point of view the packet is coming from.
Purpose	To receive all packets (non-networking packets as well as packets from all network).
Syntax	void setNetworkFilteringOff ()
Parameters	–
Return value	–
Output values	• Flag <code>_filterCurrentNetwork</code> in register <code>userInterface</code> : <code>_filterCurrentNetwork</code> : 0 - filtering off 1 - filtering on • This affects the <code>RFRXpacket</code> return value.
Preconditions	For IQMESH only. Default OS condition is Filtering Off.
Remarks	Network 1 or 2 is automatically selected according to last received packet in this mode (except of non-networking packets).
Side effects	–
See also	<code>setNetworkFilteringOn</code> , <code>RFRXpacket</code>
Example	<pre> setNetworkFilteringOff(); // Stop filtering incoming packets RFRXpacket(); // Return value == 1 if // the packet came from current network // or from non-current network(s) // or it is a non-networking packet // Return value == 0 if // no packet came in time at all </pre>

setUserAddress

Function	Assign a user address to a Node
Purpose	User addressing of Nodes
Syntax	<code>void setUserAddress (address)</code>
Parameters	<code>uns16 address</code> : user address 1 to 65 000
Return value	–
Output values	–
Preconditions	For IQMESH Node and DFM2B only.
Remarks	<ul style="list-style-type: none"> • 0xFFFF is intended for broadcast. • Groups can be created by assigning the same address to more Nodes. • See Routing algorithms in the IQRF OS user's guide for details. • It is often convenient to set this as a part of bonding procedure by the user (to keep user program the same for all Nodes etc.). • Node User address is stored in EEPROM and is accessible via <code>getNetworkParams</code>. See Example 4.
Side effects	–
See also	<code>bondNewNode</code>
Example 1	<code>setUserAddress(2000); // The Node has got user address 2000</code>
Example 2	<pre>setUserAddress(UA); eeWriteByte(EEUA, UA) // User address stored to EEPROM ... reset(); // User address lost after reset setUserAddress(eeReadByte(EEUA)); // User address restored from EEPROM</pre>
Example 3	<pre>getNetworkParams(); // Get User address uns16 myAddress = ntwUSERADDRESS; // See IQRF-memory.h</pre>

getNetworkParams

Function	Get network parameters
Purpose	Get some information about current system, RF and network parameters
Syntax	<code>getNetworkParams ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • param2: Address of the device in network. <ul style="list-style-type: none"> • 0 Unbonded device • 1 – 239 Bonded Node (logical address) • 254 (0xFE) Universal address (e.g. prebonded Node) • bit <code>_NTWPACKET</code> <ul style="list-style-type: none"> 1 – IQMESH packet 0 – Peer-to-peer packet • param3: Network identification (<code>param3.high=NID1, param3.low=NID0</code>). If the device is bonded <code>NID0</code> and <code>NID1</code> refer to Coordinator otherwise to the device itself. These features are not guaranteed for future OS versions. • Network parameters (registers with names beginning with the <code>ntw</code> prefix) are updated. See IQRF OS User's guide, Appendix 2, table OS, RF and network parameters.
Preconditions	For IQMESH only.
Remarks	See example E11 - IQMESH-N [10].
Side effects	–
See also	<code>amIBonded</code> , <code>removeBondAddress</code>
Example	<pre> if (amIBonded()) // Is the Node bonded? { // Yes: getNetworkParams(); // Get Node number myAddr = param2; } </pre>

sendFRC

Function	Fast Response Command (FRC) by the Coordinator and request for fast answer from all Nodes
Purpose	Send a command requesting fast data collection from all Nodes
Syntax	uns8 sendFRC (cmd)
Parameters	<p>uns8 cmd: User command. It is copied to MPRW1 on Node side.</p> <ul style="list-style-type: none"> • cmd.7 Format of collected data <ul style="list-style-type: none"> • 0 Bit pairs collected. 2 bits from up to 239 Nodes (with logical addresses 1-239) • 1 Bytes collected. 1 byte from up to 62 Nodes (with logical addresses 1-62) • cmd.0 to 6 User-specific (possibly closer specifying the FRC command) <p>Additionally, the 2B register DataInSendFRC of the Coordinator is copied to 2B registers DataOutBeforeResponseFRC of all Nodes which received FRC.</p>
Return value	<ul style="list-style-type: none"> • 0x00 – 0xEF FRC successful. Number of Nodes participating in FRC (adding a value to FRC response). For bit pairs collected only. Just non-zero bit pairs are counted. • 0xF0 – 0xFD Reserved • 0xFE FRC unsuccessful. Fast return in case of not-consistency (e.g. in case of previous illegal modification of EEPROM in restricted area by the user) For bit pairs collected only. • 0xFF FRC unsuccessful, no Nodes are bonded
Output values	<ul style="list-style-type: none"> • Collected data is stored in bufferINFO (if properly answered by the Nodes) <ul style="list-style-type: none"> • When bits are collected, the 1st bits from the Nodes are stored in the bytes indexed 0-29 of the bufferINFO, 2nd bits from the Nodes are stored in the bytes indexed 32-61. Bit.0 in bufferINFO[0] and bufferINFO[32] is not used. <pre style="margin-left: 20px;"> bufferINFO [0] bufferINFO[1] ... 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 1st bit of: N7 N6 N5 N4 N3 N2 N1 - N15 N14 N13 N12 N11 N10 N9 N8 ... bufferINFO [32] bufferINFO[33] ... 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 2nd bit of: N7 N6 N5 N4 N3 N2 N1 - N15 N14 N13 N12 N11 N10 N9 N8 </pre> • When bytes are collected, they are stored at bytes 1-62 of the bufferINFO. bufferINFO[0] is not used. <pre style="margin-left: 20px;"> bufferINFO [0] [1] [2] [3] [4] ... - N1 N2 N3 N4 ... </pre>
Preconditions	For IQMESH Coordinator only (setCoordinatorMode must be called first).
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-C [10] and IQRF OS User's guide [1], chapter Fast Response Command. • Data can be collected also from not discovered Nodes. • This is a blocking function (application program is staying here until the collection is completed). This time depends on number of bonded and discovered Nodes. It can be evaluated as: $t = 0.02 \times \text{bonded Nodes} + 0.09 \times \text{discovered Nodes} + 0.11 \text{ [s]}$ The worst FRC data collection case is 26.4 s in a network with 239 discovered Nodes. • FRC works for 1 B addressing (with addresses from 1 up to 239) only. • FRC works in RF STD mode only.
Side effects	<ul style="list-style-type: none"> • Watchdog is disabled after finishing. • All OS buffers (bufferINFO, bufferCOM, bufferRF and bufferAUX) are modified • toutRF variable is changed • STAY_RX flag and other RFmode related functionality may be changed. See setRFmode. • All OS registers regarding RF communication – relating to network parameters sent in the packet, e.g. RX and RTDT0 – RTDT3 (RTHOPS, RTSLOT, ...) may be changed. • A/D converter control registers are changed
See also	responseFRC

Example	<pre> SetCoordinatorMode(); DataInSendFRC = user_value; // uns16, to be delivered to all Nodes _LEDG = 1; // FRC duration indication SendFRC(myCommand); _LEDG = 0; setWDTon(); // If WDT used - see side effects copyBufferINFO2COM(); startSPI(sizeof(bufferCOM)); </pre>
----------------	---

responseFRC

Function	Response to a packet with FRC command received by a Node
Purpose	Fast sending of collected data from more Nodes to the Coordinator
Syntax	void responseFRC ()
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • MPRW1 contains a user command sent from the Coordinator as the parameter of function <code>sendFRC</code> • Bit.7 in register MPRW1 specifies the format (the range and the type) of the response (collected) data: <ul style="list-style-type: none"> • 0 2 bits (<code>responseFRCvalue.0</code> and <code>.1</code>) – from all Nodes with logical addresses 1-239 • 1 1 byte (<code>responseFRCvalue</code>) – from Nodes with logical addresses 1-62 only
Preconditions	<ul style="list-style-type: none"> • For IQMESH Node only (<code>setNodeMode</code> must be called first). • FRC packet receiving is indicated by the <code>_MPRWF</code> flag and the MPRW0 register which must contain the <code>_FRCOMMAND</code> value. See the example below. • Before <code>responseFRC</code> calling it is necessary to wait until routing of the FRC packet from the Coordinator is finished. See the example below. • The time between finished routing and <code>responseFRC</code> calling can be long as needed, but it MUST be the SAME for ALL Nodes. See the example below. • Before <code>responseFRC</code> calling the response value (collected data) must be placed in the <code>responseFRCvalue</code> register. It is recommended to respond by non-zero values only and dedicate zero value to distinguish (by the Coordinator) the case that the response from the Node failed. (But also any other rule can be defined by the user for it instead.)
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-N [10] and IQRF OS User's guide [1], chapter Fast Response Command. • This is a blocking function (application program is staying here until the collection is completed). The time depends on: <ul style="list-style-type: none"> • Number of Nodes in the network • Whether the Node is discovered or not • Logical address or VRN • FRC works for 1 B addressing (with addresses from 1 up to 239) only. • FRC works in RF STD mode only.
Side effects	<ul style="list-style-type: none"> • Watchdog is disabled after finishing. • OS buffers <code>bufferINFO</code>, <code>bufferRF</code> and <code>bufferAUX</code> are modified • <code>toutRF</code> variable is changed • <code>STAY_RX</code> flag and other RFmode related functionality may be changed. See <code>setRFmode</code>. • All OS registers regarding RF communication – relating to network parameters sent in the packet, e.g. <code>RX</code> and <code>RTDT0</code> – <code>RTDT3</code> (<code>RTHOPS</code>, <code>RTSLOT</code>, ...) may be changed. • A/D converter control registers are changed
See also	<code>sendFRC</code>

Example

```

if (RFRXpacket())
{
    if (_ROUTEF)           // Has the packet been routed?
    {
        // Yes - wait for finish of routing
        while (RTHOPS)    // Rest of hops
        {
            waitDelay(RTTSLOT);
            RTHOPS--;
        }
    }

    // FRC command handling
    // Is it an FRC packet?
    if (_MPRWF && (MPRW0 == __FRCOMMAND))
    {
        uns16 user_value = DataOutBeforeResponseFRC; // A value received from
                                                    // the Coordinator (from register DataInSendFRC)

        ... // Do something according to MPRW1 command
            // (and possibly according to DataOutBeforeResponseFRC)
            // e.g. myResponse = ...;
            // Shaded part must take the same time for all Nodes

        if (MPRW1.7)
            responseFRCvalue = myResponse;           // Byte value
        else
            responseFRCvalue = myResponse & 0x03;    // 2 bit value

        responseFRC(); // Blocking time - see Remarks
        setWDTon();   // If WDT used - see side effects
    }
    else // Non FRC command handling
    {
        ...
    }
}

```

Routing

setRoutingOn

Function	Routing enabled
Purpose	Allow the Node to route packets on background.
Syntax	<code>void setRoutingOn ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • Enables to assign a VRN (Virtual Routing Number) to the Node during Discovery • Flag <code>_disableRouting = 0</code> • This state is stored in EEPROM and initialized after reset.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Nodes only • For DFM routing algorithms only
Remarks	<ul style="list-style-type: none"> • Routing must be enabled for a Node to be assigned to the routing backbone during Discovery. • Routing can be enabled in all receive modes (STD, LP, XLP and RFIM). • Flag <code>_disableRouting</code> in register <code>_ntwCFG</code> is available read only after calling <code>getNetworkParams</code>: <ul style="list-style-type: none"> <code>_disabledRouting: 0</code> – Routing on <code>_disabledRouting: 1</code> – Routing off
Side effects	–
See also	<code>setRoutingOff</code> , <code>discovery</code> , <code>isDiscoveredNode</code> , <code>wasRouted</code>
Example	–

setRoutingOff

Function	Routing disabled
Purpose	Forbid the Node to route packets on background.
Syntax	<code>void setRoutingOff ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • Disables to assign a VRN (Virtual Routing Number) to the Node during Discovery • Flag <code>_disableRouting = 1</code> • This state is stored in EEPROM and initialized after reset.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Nodes only • For DFM routing algorithms only
Remarks	<ul style="list-style-type: none"> • If routing is disabled the Node will not be assigned to the routing backbone during Discovery. • Flag <code>_disableRouting</code> in register <code>_ntwCFG</code> is available read only after calling <code>getNetworkParams</code>: <ul style="list-style-type: none"> <code>_disabledRouting: 0</code> – Routing on <code>_disabledRouting: 1</code> – Routing off
Side effects	–
See also	<code>setRoutingOn</code> , <code>discovery</code> , <code>isDiscoveredNode</code> , <code>wasRouted</code>
Example	–

discovery

Function	Discover Nodes for routing and assign VRN (Virtual Routing Number) to individual Nodes
Purpose	Routing backbone creation (for routing transparent from the user's point of view)
Syntax	<code>uns8 discovery (MaxNodeAddr)</code>
Parameters	<p><code>uns8: MaxNodeAddr</code>: Maximum address of the node to be participating in the discovery process.</p> <ul style="list-style-type: none"> • 1 to 239 Specified value is applied • 0 Number of bonded Nodes is applied
Return value	Number of discovered Nodes (\leq number of Nodes which should route specified as routers (by...))
Output values	<ul style="list-style-type: none"> • Routing address area (1 – 239) is split into two parts: <ul style="list-style-type: none"> • Devices with addresses from 1 to <code>MaxNodeAddr</code> will be part of the discovery process, that is why they will become routers • Devices with addresses from <code>MaxAddr+1</code> to 239 will not be routers. See IQRF OS guide for more information. • Routing backbone is stored in EEPROM
Preconditions	<ul style="list-style-type: none"> • For IQMESH Coordinator only. • Must be performed in STD RX mode only. • Nodes must be in the <code>answerSystemPacket</code> loop routine during Discovery. • LED indication of passing discovery can be disabled (to save power consumption) or enabled (for development, service or demonstration) by the <code>_systemLEDindication</code> bit variable from OS v3.04D. Default is disabled (<code>_systemLEDindication=0</code>). • SPI must not run in background during <code>discovery</code>
Remarks	<ul style="list-style-type: none"> • Nodes in current network only are discovered. • Discovery should be invoked after every change in network topology. • Nodes use the TX output power currently set in Coordinator during the discovery process. • It is recommended to run <code>discovery</code> under stronger conditions than ones that will be used in normal communication. It can be achieved by lower RF power. • See example E11-IQMESH-C [10]. • See IQRF OS User's guide, routing algorithms.
Side effects	<ul style="list-style-type: none"> • Watchdog is disabled during this operation and enabled after finishing. • All OS buffers (<code>bufferINFO</code>, <code>bufferCOM</code>, <code>bufferRF</code> and <code>bufferAUX</code>) are modified • <code>toutRF</code> variable is changed • <code>STAY_RX</code> flag and other RFmode related functionality may be changed. See <code>setRFmode</code>. • All OS registers regarding RF communication – relating to network parameters sent in the packet, e.g. <code>RX</code> and <code>RTDT0 – RTDT3</code> (<code>RTHOPS</code>, <code>RTTSLOT</code>, ...) may be changed. • A/D converter control registers are changed
See also	<code>setRoutingOn</code> , <code>setRoutingOff</code> , <code>isDiscoveredNode</code> , <code>bondNewNode</code> , <code>answerSystemPacket</code>
Example 1	<pre>setTXpower(DISCOVERY_POWER); // Set RF power for discovery setRFmode(_RX_STD); // Set STD RX mode nodes = discovery(10); // Routers with addresses 1 to 10 SWDTEN = 0; // Possibly restore WDT setRFmode(MY_RFMODE); // Restore RF mode parameters setTXpower(MY_POWER); // Restore RF power</pre>
Example 2	<pre>nodes = discovery(eeReadByte(0x00)); // Limit to number of bonded Nodes</pre>

answerSystemPacket

Function	Enable response to Coordinator for Discovery and Node authorization
Purpose	Discovery and Node authorization (during remote bonding) support from the Node's side
Syntax	<code>void answerSystemPacket ()</code>
Parameters	–
Return value	–
Output values	System information exchanged between Coordinator and the Node via system packets.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Node only. • Must be performed in STD RX mode only. • Nodes must be in the <code>answerSystemPacket</code> loop routine when Discovery or Node authorization is running. • WDT should be disabled before <code>answerSystemPacket</code>
Remarks	<ul style="list-style-type: none"> • Nodes use the TX output power currently set in Coordinator for discovery. • It is recommended to run <code>discovery</code> under stronger conditions than ones that will be used in normal communication. It can be achieved by lower RF power.
Side effects	<ul style="list-style-type: none"> • <code>toutRF</code> is modified • TX power can be affected during Discovery process • <code>STAY_RX</code> flag and other RFmode related functionality may be changed. See <code>setRFmode</code>. • All OS registers regarding RF communication – relating to network parameters sent in the packet, e.g. <code>RX</code> and <code>RTDT0 – RTDT3</code> (<code>RTHOPS</code>, <code>RTTSLOT</code>, ...) may be changed. • A/D converter control registers are modified.
See also	<code>setRoutingOn</code> , <code>setRoutingOff</code> , <code>isDiscoveredNode</code> , <code>discovery</code> , <code>nodeAuthorization</code>
Example	<pre> toutRF = MY_TOUT_RF; if (RFRXpacket ()) { ... } else { setWDToff (); answerSystemPacket (); // to be discovered setWDTon (); setTXpower (MY_POWER); // Restore } </pre>

isDiscoveredNode

Function	Check for being discovered
Purpose	Ask whether the Node has been discovered
Syntax	bit <code>isDiscoveredNode (address)</code>
Parameters	uns8: address: Node address
Return value	<ul style="list-style-type: none"> • true: Specified Node has been discovered • false: Specified Node has not been discovered
Output values	–
Preconditions	For IQMESH Coordinator only.
Remarks	See E11-IQMESH-C [10].
Side effects	–
See also	discovery, answerSystemPacket, optimizeHops
Example	<pre> DiscoveredNodes = discovery(3); // Discovery (up to 3 zones) if (DiscoveredNodes < BondedNodes) // (BondedNodes and DiscoveredNodes // are user variables) { // There are some bonded but not discovered Nodes if (isDiscoveredNode(1)) // Is the Node 1 discovered? ... } else { // All bonded Nodes discovered ... } </pre>

wasRouted

Function	Indicate incoming packet routing
Purpose	To distinguish whether incoming packet has been routed for other recipient(s).
Syntax	bit <code>wasRouted ()</code>
Parameters	–
Return value	<ul style="list-style-type: none"> • true packet has been routed • false packet has not been routed
Output values	–
Preconditions	For IQMESH Nodes only.
Remarks	Addressees route broadcast packets only. See E11-IQMESH-N [10].
Side effects	–
See also	setRoutingOn, setRoutingOff, discovery, isDiscoveredNode
Example	<pre> if (RFRXpacket ()) { if (wasRouted ()) pulseLEDG (); // indicate routing received packet for broadcast ... } else { if (wasRouted ()) pulseLEDG (); // indicate routing incoming packet for another addressee } </pre>

optimizeHops

Function	Optimize number of hops for given Node
Purpose	Set optimized number of hops according to a topology, without flooding
Syntax	<code>void optimizeHops (x)</code>
Parameters	<p><code>uns8 x</code>: optimizing method</p> <ul style="list-style-type: none"> • <code>0xFF</code> DOM – Discovered optimized MESH: sets <code>RTHOPS</code> to <code>VRN</code> of addressed Node • <code>0x00</code> DRM – Discovered reduced MESH: sets <code>RTHOPS</code> to <code>VRN</code> of the first Node in the zone of the addressed Node.
Return value	–
Output values	<code>RTHOPS</code> (number of hops) is set
Preconditions	<ul style="list-style-type: none"> • For IQMESH Coordinator and DFM routing algorithm only. • Intended to be called before sending a packet from Coordinator. • Node address must be set before (<code>RX = ...</code>). • The Node must be discovered.
Remarks	See E11-IQMESH-C [10] and IQRF OS User's guide.
Side effects	–
See also	<code>discovery</code> , <code>isDiscoveredNode</code>
Example	<pre> setCoordinatorMode (); RX = MY_NODE; RTHOPS = eeReadByte (0x00); // Hops according to a number of bonded Nodes if (isDiscoveredNode (RX)) // For routing using Discovery only optimizeHops (0xFF); // Modifies RTHOPS (number of hops) : : RFTXpacket (); </pre>

Bonding – Node only

bondRequestAdvanced

Function	Ask Coordinator for bonding or other Node or Coordinator for prebonding to the network via RF. Bond the Node in cooperation with the Coordinator or prebond the Node in cooperation with an already bonded Node or the Coordinator and record it to EEPROM. See IQRF User's guide, chapter <i>Bonding</i> for more information.
Purpose	Request by the Node to be included to the network on both Coordinator's and Node's sides. Moreover, a 2 B user data is exchanged between prebonded device and the device providing prebonding.
Syntax	bit <code>bondRequestAdvanced ()</code>
Parameters	<code>uns16 DataInBondRequestAdvanced</code> User data passed to the device providing prebonding (to be stored in the <code>DataOutPrebondNode</code> variable). For prebonding only.
Return value	<ul style="list-style-type: none"> • 1 – Node has been bonded • 0 – Node has not been bonded
Output values	<ul style="list-style-type: none"> • The <code>amIBonded</code> function starts to return value == 1 whenever is called while the Node is bonded by <code>bondRequestAdvanced</code> not beeing unbonded by <code>removeBond</code>. • Every <code>bondRequestAdvanced</code> calling increments the value of the internal counter (it is sent with the request). This counter is used with the <code>bondingMask</code> register to handle the situation when more than one Node with enabled prebonding would response to the request. See functions <code>bondNewNode</code> and <code>prebondNode</code> and IQRF User's guide, chapter <i>Bonding</i>. The counter is cleared after reset. • <code>uns16 DataOutBondRequestAdvanced</code> – User data passed from device providing prebonding (parameter <code>DataInPrebondNode</code> of function <code>prebondNode</code>). For prebonding only.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Node only (<code>setNodeMode</code> must be called first)
Remarks	<ul style="list-style-type: none"> • Bonding is a mutual relationship between Coordinator and Node. Coordinator assigns a Node number (1 to 239 or 0xFE) to the Node which serves as Node address within the network. (Coordinator itself has the address 0.) Bonding accomplishes via exchanging system RF packets and results are stored in system part of internal EEPROMs. The user can access results and change them via other bonding functions. See example E11-IQMESH-DFM-N, E11-IQMESH-DFM-C [10]. • Prebonding is an initial phase of remote bonding. The new (bond requesting) Node gets the network ID and the universal address 0xFE from another (already bonded) Node or the Coordinator. So the new Node becomes accessible in given network and can be authorized by the Coordinator to get a requested address. • This function takes cca 60 ms. It sends just one request for bonding and then waits for some time for the confirmation. This is the main difference between the recent <code>bondRequest</code> function which sends the request repeatedly for cca 10 s. • RF power and RF channel is not affected. STD mode is used. • The assigned address can be found out by function <code>getNetworkParams</code>.
Side effects	<ul style="list-style-type: none"> • <code>DLEN</code>, <code>PIN</code>, <code>toutRF</code>, <code>bufferRF</code> and <code>bufferINFO</code> are modified. • IQMESH mode must be restored by <code>setNodeMode</code> after <code>bondRequestAdvanced</code>. • A/D converter control registers are modified.
See also	<code>bondNewNode</code> , <code>amIBonded</code> , <code>removeBond</code> , <code>rebondNode</code> , <code>getNetworkParams</code> , <code>setNodeMode</code> , <code>prebondNode</code> , <code>nodeAuthorization</code>

Example	<pre> while (!amIBonded()) // Request for beeing bonded (if not bonded yet) { clrwdt(); // If WDT active pulseLEDG(); DataInBondRequestAdvanced = user_in_value; // uns16, to be delivered to // the device that provides prebonding // (to register DataOutPrebondNode) if (bondRequestAdvanced()) // Repeatedly try to bond { pulseLEDR(); uns16 user_out_value = DataOutBondRequestAdvanced; // A value received // from the device that provides prebonding // (from register DataInPrebondNode) } waitDelay(1); } // Until successful setNodeMode(); // Restore </pre>
----------------	--

bondRequest - obsolete

Function	Ask Coordinator via RF for bonding to its network. Bond the Node in cooperation with Coordinator and record it to EEPROM.
Purpose	Request by the Node to be included to the network on both Coordinator's and Node's sides.
Syntax	bit <code>bondRequest()</code>
Parameters	–
Return value	<ul style="list-style-type: none"> • 1 – Node has been bonded • 0 – Node has not been bonded
Output values	<ul style="list-style-type: none"> • The <code>amIBonded</code> function starts to return value == 1 whenever is called while the Node is bonded by <code>bondRequest</code> not beeing unbonded by <code>removeBond</code>. • Coordinator is not affected at all. • <code>param2</code>: Node address (if successfully bonded only). Not guarranted for future OS versions.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Node only (<code>setNodeMode</code> must be called first)
Remarks	<ul style="list-style-type: none"> • Bonding is a mutual relationship between Coordinator and Node. Coordinator assigns a Node number (1 to 239 or 0xFE) to the Node which serves as Node address within the network. (Coordinator itself has the address 0.) Bonding accomplishes via exchanging system RF packets and results are stored in system part of internal EEPROMs. The user can access results and change them via other functions related to bonding. See example E11 - IQMESH-N, E11 - IQMESH-C [10]. This function is active until successfully finished or fixed 10 s timeout expired. RF power is not affected.
Side effects	<ul style="list-style-type: none"> • <code>DLEN</code>, <code>PIN</code>, <code>toutRF</code>, <code>bufferRF</code> and <code>bufferINFO</code> are modified • Result of <code>captureTicks</code> is destroyed if <code>startCapture</code> is active on background at the same time. • Watchdog is disabled during this operation and enabled after finishing • IQMESH mode must be restored by <code>setNodeMode</code> after <code>bondRequest</code> • A/D converter control registers are modified
See also	<code>bondNewNode</code> , <code>amIBonded</code> , <code>removeBond</code> , <code>rebondNode</code> , <code>getNetworkParams</code> , <code>setNodeMode</code>
Example 1	<pre> pulsingLED(); // LED blinking indicates attempt to bond (max. 10 s) if (bondRequest()) { // if successfully bonded stopLED(); _RLED=1; // LED On waitDelay(100); // for 1 s } setNodeMode(); // Restore stopLED(); </pre>
Example 2	See <code>amIBonded</code>

amIBonded

Function	Is the Node bonded?
Purpose	Test whether the Node is bonded on Node's side
Syntax	bit amIBonded ()
Parameters	–
Return value	<ul style="list-style-type: none"> • 1 – Node is bonded (after <code>bondRequestAdvanced</code>, not being unbonded by <code>removeBond</code>) • 0 – Node is not bonded: <ul style="list-style-type: none"> • no <code>bondRequestAdvanced</code> has ever been successfully executed • after <code>removeBond</code>
Output values	–
Preconditions	For IQMESH Node only (<code>setNodeMode</code> must be called first) .
Remarks	See example E11-IQMESH-DFM-N [10].
Side effects	–
See also	<code>bondRequestAdvanced</code> , <code>removeBond</code> , <code>removeBondAddress</code>
Example	<pre>while (!amIBonded()) // Request for being bonded (if not bonded yet) { bondRequestAdvanced(); // Repeatedly try to bond clrwdt(); // If WDT active } // Until successful</pre>

removeBondAddress

Function	Change logical Node address to the universal one (0xFE). NID stays unchanged, therefore the Node still stays in the network.
Purpose	E.g. to enable subsequent change of the Node address.
Syntax	void removeBondAddress ()
Parameters	–
Return value	-
Output values	–
Preconditions	For IQMESH Node only (<code>setNodeMode</code> must be called first).
Remarks	<ul style="list-style-type: none"> • <code>removeBondAddress</code> relates to the Node only. The other side is not informed by OS about changes made by these function. If synchronization is needed it should be done by the application. • To enable possible addressing of the Node in the group of Nodes with universal address, it is recommended to save the MID of given Node by the application first.
Side effects	–
See also	<code>amIBonded</code> , <code>getNetworkParams</code> , <code>nodeAthorization</code>
Example	<code>removeBondAddress();</code> // Change current logical address to universal address

removeBond

Function	Remove the Node from the network and record it to EEPROM.
Purpose	Exclude the Node from the network on Node's side.
Syntax	<code>void removeBond ()</code>
Parameters	–
Return value	–
Output values	<ul style="list-style-type: none"> • The <code>amIBonded</code> function starts to return value == 0 whenever is called until the Node is bonded again via <code>bondRequestAdvanced</code>. • Coordinator is not affected at all.
Preconditions	For IQMESH Node only (<code>setNodeMode</code> must be called first).
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-N [10]. • For rebonding use <code>bondRequestAdvanced</code> again. • <code>removeBond</code> relates to the Node only and <code>removeBondedNode</code> and <code>rebondNode</code> relate to Coordinator only. The other side is not informed by OS about changes made by these functions. If synchronization is needed it should be done by the application.
Side effects	–
See also	<code>bondRequestAdvanced</code> , <code>bondNewNode</code> , <code>amIBonded</code> , <code>rebondNode</code>
Example	<code>removeBond(); // Remove the bond</code>

Bonding – Coordinator only

bondNewNode

Function	Local bonding. Looking for bond requesting devices and bond a new Node by Coordinator on a Node's request via RF in direct range. Allocate the Node number and assign the Network ID and send both to the Node via RF. If successful, the Node is bonded to the network on both Coordinator's and Node's sides and is included to the list of bonded Nodes provided by the Coordinator in EEPROM.
Purpose	Include a new Node in direct range to the network
Syntax	bit <code>bondNewNode (address)</code>
Parameters	<p>uns8: address</p> <ul style="list-style-type: none"> • 1 to 239 Assign requested address to the Node. This must be unique in the whole network. If an existing number is used the Node is not bonded and the function immediately returns 0. Only these Nodes can be parts of routing backbone. • 0 The first free address is assigned. It equals to the number of bonded nodes + 1. It assumes a continuous block of addresses and possible vacations are ignored. Thus, this way is suitable for the initial bonding without discontinuities only. • 254 (0xFE) The universal address. Nodes with this address are included in the network but outside the routing backbone (not being discovered). Requested address can be assigned by <code>setUserAddress</code>. It is intended especially for networks with more than 239 Nodes.
Return value	<ul style="list-style-type: none"> • 1 – bonding successful, the Node is included to the list of bonded Nodes • 0 – bonding unsuccessful, the Node is not included to the list of bonded Nodes
Output values	<ul style="list-style-type: none"> • <code>param2</code>: Node number • <code>bufferRF[0 to 1]</code>: two lower ID bytes of the bonded Node, LSB in <code>bufferRF[0]</code>. • The <code>isBondedNode</code> function starts to return value == 1 whenever is called while the Node is in the list of bonded Nodes.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Coordinator only. (<code>setCoordinatorMode</code> must be called first.) • The Coordinator accomplishes bonding on request from a Node via RF. When this function is executing the <code>bondRequestAdvanced</code> function must be called in the Node.
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-C [10] and IQRF OS User's guide, chapter Bonding. • If no requesting Node is detected during 10 s period this function terminates and returns 0. • Network ID is derived from Coordinator ID which ensures unique identification of various networks. • RF power and RF channel is not affected. The STD mode is used. • An occupied address can be unblocked by <code>removeBondedNode (address)</code>. • The function responds to bond request only if the following internal condition is valid: <pre>if (((counter ^ address) & bondingMask) == 0)</pre> See <code>prebondNode</code> Remarks for description.
Side effects	<p>The following values are modified and not restored:</p> <ul style="list-style-type: none"> • <code>PIN</code>, <code>DLEN</code>, <code>toutRF</code>, <code>bufferRF</code> and <code>bufferINFO</code> are modified • Result of <code>captureTicks</code> is destroyed if <code>startCapture</code> is active on background at the same time. • Watchdog is disabled during this operation and enabled after finishing. • IQMESH mode must be restored by <code>setCoordinatorMode</code> after <code>bondNewNode</code> • A/D converter control registers are modified
See also	<code>bondRequestAdvanced</code> , <code>removeBondedNode</code> , <code>rebondNode</code> , <code>isBondedNode</code> , <code>setUserAddress</code> , <code>setCoordinatorMode</code> , <code>nodeAuthorization</code> , <code>prebondNode</code>
Example	<pre>if (bondNewNode(address)) // Bonding successful ? { // Yes: NodeNumber = param2; ... } else { // No: ... // Arrange necessary steps } setCoordinatorMode(); // Restore</pre>

nodeAuthorization

Function	Authorize the prebonded Node. Allocate the Node number and send it to the prebonded Node via RF network. If successful, the Node is bonded to the network on both Coordinator's and Node's sides and is included to the list of bonded Nodes provided by Coordinator in EEPROM.
Purpose	Include a new (prebonded) Node to the network. A last phase of the remote bonding process.
Syntax	bit <code>nodeAuthorization (mid, address)</code>
Parameters	<p>uns16 mid: 2 lower bytes of MID of prebonded Node to be authorized (HB = mid[0], LB = mid[1]).</p> <p>uns8 address:</p> <ul style="list-style-type: none"> • 1 to 239 Assign requested address to the prebonded Node. This must be unique in the whole network. If an existing number is used the Node is not authorized and the function immediately returns 0. Only these Nodes can be parts of routing backbone. • 0 The first free address is assigned. It equals to the number of bonded nodes + 1. It assumes a continuous block of addresses and possible vacations are ignored. Thus, this way is suitable for the initial bonding without discontinuities. • 0xFE The universal address. Nodes with this address are included in the network but outside the routing backbone (not being discovered). Requested address can be assigned by <code>setUserAddress</code>. It is intended especially for networks with more than 239 Nodes.
Return value	<ul style="list-style-type: none"> • 1 – The requested address was free. The Node is included into the list of bonded Nodes. The result must be verified by application program, e.g. by subsequent sending a packet from the Coordinator to the authorized Node. If the authorization failed, given address must be released by <code>removeBondedNode</code> and the authorization should be repeated. • 0 – Authorization unsuccessful, the requested address is already used. The Node is not included into the list of bonded Nodes.
Output values	<ul style="list-style-type: none"> • The <code>isBondedNode</code> function starts to return value == 1 whenever is called while the Node is in the list of bonded Nodes.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Coordinator only. (<code>setCoordinatorMode</code> must be called first.) • Authorized Node must already be prebonded. • Authorized Node must be in the <code>answerSystemPacket</code> loop routine during Athorization.
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-C [10] and IQRF OS User's guide – Bonding. • This function sends an authorization packet (broadcast), does not wait for delivery and provides no checking. Therefore it is necessary to wait before sending the packet testing the result of the authorization till the authorization packet itself reaches the destination. This period to wait can be evaluated: number of routers in the network x time slot 50 ms. • An occupied address can be unblocked by <code>removeBondedNode (address)</code>. • RF power and RF channel is not affected. The STD mode is used.
Side effects	<ul style="list-style-type: none"> • PIN, DLEN, <code>bufferRF</code> and <code>bufferINFO</code> are modified
See also	<code>bondNewNode</code> , <code>prebondNode</code> , <code>removeBondedNode</code> , <code>isBondedNode</code> , <code>setUserAddress</code> , <code>setCoordinatorMode</code> , <code>bondRequestAdvanced</code> , <code>answerSystemPacket</code> , <code>removeBondAddress</code>

Example	<pre> uns16 mid; mid.high8 = MID_0; mid.low8 = MID_1; if (nodeAuthorization(mid, address)) // Was the address free? { // Yes: // Wait until authorization packet is delivered ... // Send test packet to given address if (ping successful) { // Yes: successful authorization ... } else { // No: unsuccessful authorization removeBondedNode(address); } } else { // No: // Address is occupied ... } setCoordinatorMode(); // Restore </pre>
----------------	---

isBondedNode

Function	Is specified Node in the list of bonded Nodes?
Purpose	Test whether the Node is bonded on Coordinator's side
Syntax	bit isBondedNode (n)
Parameters	uns8 n: Node number
Return value	<ul style="list-style-type: none"> • 1 – Node is in the list of bonded Nodes • 0 – Node is not in the list of bonded Nodes
Output values	–
Preconditions	For IQMESH Coordinator only. (setCoordinatorMode must be called first.)
Remarks	–
Side effects	–
See also	bondNewNode, removeBondedNode, rebondNode, clearAllBonds, nodeAuthorization
Example	<pre> if (isBondedNode(28)) // Is Node #28 bonded ? { // Yes: ... // Coordinator assumes Node #28 to be bonded } else { // No: ... // Coordinator assumes Node #28 not to be bonded } </pre>

removeBondedNode

Function	Remove a Node from the list of bonded Nodes by Coordinator in EEPROM
Purpose	Exclude the Node from the network on Coordinator's side
Syntax	<code>void removeBondedNode (n)</code>
Parameters	<code>uns8 n</code> : Node number
Return value	–
Output values	The <code>isBondedNode</code> function starts to return value == 0 whenever is called while the Node is not in the list of bonded Nodes. The Node is not affected at all.
Preconditions	For IQMESH Coordinator only. (<code>setCoordinatorMode</code> must be called first.)
Remarks	<code>removeBondedNode</code> and <code>rebondNode</code> relate to Coordinator only and <code>removeBond</code> relates to Node only. The other side is not informed by OS about changes made by these functions. If synchronization is needed it should be done by the application.
Side effects	–
See also	<code>bondNewNode</code> , <code>isBondedNode</code> , <code>clearAllBonds</code> , <code>removeBond</code>
Example	<pre>removeBondedNode(28); // Coordinator assumes Node #28 to be // out of the network from now on</pre>

rebondNode

Function	Put a Node back to the list of bonded Nodes by Coordinator in EEPROM
Purpose	Include the Node to the network again on Coordinator's side
Syntax	<code>bit rebondNode (n)</code>
Parameters	<code>uns8 n</code> : Node number
Return value	reserved for future OS versions
Output values	The <code>isBondedNode</code> function starts to return value == 1 whenever is called while the Node is in the list of bonded Nodes. The Node is not affected at all.
Preconditions	<ul style="list-style-type: none"> • For IQMESH Coordinator only. (<code>setCoordinatorMode</code> must be called first.) • Avoid rebonding a Node not being bonded ever before.
Remarks	<code>removeBondedNode</code> and <code>rebondNode</code> relate to Coordinator only and <code>removeBond</code> relates to Node only. The other side is not informed by OS about changes made by these functions. If synchronization is needed it should be done by the application.
Side effects	–
See also	<code>bondNewNode</code> , <code>removeBondedNode</code> , <code>isBondedNode</code>
Example	<pre>rebondNode(28); // Coordinator assumes Node #28 to be // back in the network from now on</pre>

clearAllBonds

Function	Remove all Nodes from the list of bonded Nodes by Coordinator in EEPROM
Purpose	Excluding all Nodes from the network on Coordinator's side
Syntax	<code>void clearAllBonds ()</code>
Parameters	–
Return value	–
Output values	The <code>isBondedNode</code> function starts to return value <code>== 0</code> whenever is called while the Node is not in the list of bonded Nodes. Nodes are not affected at all.
Preconditions	For IQMESH Coordinator only. (<code>setCoordinatorMode</code> must be called first.)
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-C [10]. • After subsequent <code>bondNewNode(0)</code> the Coordinator will start to assign Node numbers from 0.
Side effects	<code>bufferINFO</code> modified
See also	<code>removeBondedNode</code>
Example	<code>clearAllBonds (); // Exclude all currently bonded nodes from the network</code>

Bonding – Node and Coordinator

prebondNode

Function	Look for bond requesting devices and prebond a new Node based on its request via RF. Assign the universal address 0xFE and Network ID and send both to the new Node via RF and get back Module ID (MID) of this new Node.
Purpose	Prebond a new Node to the network. This is the first phase of the remote bonding process and possibly operates even without direct action of the Coordinator. Then it is needed to deliver the obtained MID to the Coordinator (the second phase, not necessary for prebonding by the Coordinator) by the application program. To complete remote bonding, the Coordinator must authorize the new Node (the third phase of the remote bonding process). Moreover, a 2 B user data is exchanged between prebonded device and the device providing prebonding.
Syntax	bit prebondNode ()
Parameters	–
Return value	<ul style="list-style-type: none"> • 1 – prebonding successful. <code>bufferINFO</code> contains MID of prebonded Node • 0 – prebonding unsuccessful. <code>bufferINFO</code> unchanged
Input values	<code>uns16 DataInPrebondNode</code> : User data to be delivered to the prebonded Node (to <code>DataOutBondRequestAdvanced</code>)
Output values	<ul style="list-style-type: none"> • <code>bufferINFO[0 to 3]</code>: MID of the prebondedNode (if successfully prebonded), LSB in <code>bufferINFO[0]</code>. • <code>uns16 DataOutPrebondNode</code>: User data received from the prebonded Node (from <code>DataInBondRequestAdvanced</code>)
Preconditions	<ul style="list-style-type: none"> • For IQMESH only (<code>setNodeMode</code> or <code>setCoordinatorMode</code> must be called first). • The Node providing prebonding must already be bonded in given network (to be able to provide the Network ID) and must be accessible from the Coordinator (either directly or via other Nodes). This is no use in case of prebonding by the Coordinator. • While the new Node is requesting to be prebonded (by function <code>bondRequestAdvanced</code>), the <code>prebondNode</code> function must be called in RF RX loop. See the Example below.
Remarks	<ul style="list-style-type: none"> • See example E11-IQMESH-DFM-N [10] and IQRF OS User's guide, chapter Bonding. • It is recommended to activate this function in application SW just in periods when it is actually needed. See the <code>prebondingEnabled</code> flag in the Example below. Permanent activation can ask for troubles with unwanted prebonding. If more Nodes have activated prebonding, it should be found out which Node has prebonded the new Node and ensure delivering of received MID to the Coordinator. • RF power and RF channel is not affected. The STD mode is used. • The function responds to bond request only if the following internal condition is valid: <pre>if (((counter ^ address) & bondingMask) == 0)</pre> <ul style="list-style-type: none"> <code>counter</code> Request for bonding contains a counter cleared after reset and incremented after every <code>bondRequestAdvanced()</code> call. <code>address</code> Address of the device providing prebonding (evaluating the condition above). <code>bondingMask</code> User-accessible register (with default value 0, i.e. the condition is true independently on the <code>counter</code> as well as the <code>address</code>). See IQRF User's guide, chapter Bonding for more information about the <code>bondingMask</code> usage.
Side effects	<p>The following values are modified and not restored:</p> <ul style="list-style-type: none"> • <code>PIN</code>, <code>DLEN</code>, <code>bufferRF</code> and <code>bufferINFO</code> are modified • IQMESH mode be restored by <code>setNodeMode</code> or <code>setCoordinatorMode</code> after <code>prebondNode</code> • A/D converter control registers are modified
See also	<code>bondRequestAdvanced</code> , <code>setNodeMode</code> , <code>setCoordinatorMode</code> , <code>nodeAuthorization</code> , <code>answerSystemPacket</code>

Example

```
if (RFRXpacket())
{
    ...
}
else
{
    DataInPrebondNode = user_in_value; // uns16, to be delivered to prebonded
    // Node (to register DataOutBondRequestAdvanced)
    // Try prebonding if enabled by user
    if (prebondingEnabled && prebondNode())
    {
        setNodeMode(); // Restore
        ... // MID of prebonded Node is stored in bufferINFO
        uns16 user_out_value = DataOutPrebondNode; // A value received from
        // prebonded Node (from register DataInBondRequestAdvanced)
    }
    ...
}
```

RFPGM – wireless upload
enableRFPGM

Function	Request to configure OS for switching to RFPGM mode after TR module reset
Purpose	Enable switching to RFPGM mode after reset
Syntax	<code>void enableRFPGM()</code>
Parameters	–
Return value	–
Output values	IQRF OS is reconfigured. This function overrides the setting by <i>TR Configuration</i> performed in IQRF IDE.
Preconditions	
Remarks	This function must be executed first to modify OS and just the following reset will switch to RFPGM.
Side effects	–
See also	<code>disableRFPGM</code> , <code>runRFPGM</code> , <code>setupRFPGM</code>
Example 1	<pre>void APPLICATION() { enableRFPGM(); ... }</pre>
Example 2	See <code>disableRFPGM</code>

disableRFPGM

Function	Request to configure OS for not switching to RFPGM mode after TR module reset
Purpose	Disable switching to RFPGM mode after reset
Syntax	<code>void disableRFPGM()</code>
Parameters	–
Return value	–
Output values	IQRF OS is reconfigured. This function overrides the setting by <i>TR Configuration</i> performed in IQRF IDE.
Preconditions	–
Remarks	This function must be executed first to modify OS and just the following reset will not switch to RFPGM.
Side effects	–
See also	<code>enableRFPGM</code> , <code>setupRFPGM</code>
Example 1	<pre>enableRFPGM(); // During development // disableRFPGM();</pre>
Example 2	<pre>// enableRFPGM(); disableRFPGM(); // For final application</pre>

runRFPGM

Function	Switch to RFPGM mode
Purpose	One-shot immediate switching to RFPGM mode
Syntax	<code>void runRFPGM()</code>
Parameters	–
Return value	–
Output values	RFPGM mode initiated
Preconditions	<ul style="list-style-type: none"> • Non-networking modes and 19.2 kb/s bit rate must be selected. • Filtering of incoming packets must be disabled. (Use <code>setNetworkFilteringOff</code> if enabled.) • All user peripherals (UART, Timer6,...) used must have their interrupt enable flags (<code>TXIE</code>, <code>TMR6IE</code>,...) disabled first. • User interrupt must be disabled then. Observe the given order. See Example 2.
Remarks	<ul style="list-style-type: none"> • RF programming uses RF band and RF channel according to TR module configuration. • RFPGM mode can be refused: <ul style="list-style-type: none"> • By low level on dedicated pin (if enabled). See <code>setupRFPGM</code> Parameters. • By the <i>End RFPGM</i> button in IQRF IDE (unconditionally) • ~1 minute after entering RFPGM mode (if enabled) • After RFPGM finishing the application is always reset (regardless to RFPGM upload result). • After unsuccessful RFPGM upload the TR stays in RFPGM mode, see IQRF OS User's guide, Appendix 3 (RFPGM).
Side effects	–
See also	<code>enableRFPGM</code> , <code>setupRFPGM</code>
Example 1	<pre>void APPLICATION() ... if (jumperSet) { runRFPGM(); // Enter RFPGM mode on special request }</pre>
Example 2	<pre>RCIE = 0; // All user peripheral interrupts must be TMR6IE = 0; // disabled here (if used) // E.g. UART RX interrupt disable _enableUserInterrupt = 0; // E.g. Timer 6 interrupt disable // Needed just if user interrupt is used // It must be called not until all user // peripheral interrupt enable flags are cleared, // see above. setNonetMode(); // Disable networking (if enabled) runRFPGM(); // Run on channel(s) according to TR configuration</pre>

setupRFPGM

Function	Setup RFPGM parameters																		
Purpose	Configure RFPGM behavior																		
Syntax	void setupRFPGM(x)																		
Parameters	<p>uns8 x: Factory default: 0x83</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 10%;">bit</th> <th style="width: 15%;">7</th> <th style="width: 15%;">6</th> <th style="width: 5%;">5</th> <th style="width: 5%;">4</th> <th style="width: 5%;">3</th> <th style="width: 5%;">2</th> <th style="width: 5%;">1</th> <th style="width: 5%;">0</th> </tr> </thead> <tbody> <tr> <td></td> <td>RFPGM termination by MCU pin(s)</td> <td>RFPGM termination after ~1 min</td> <td style="text-align: center;">0</td> <td>RFPGM enable</td> <td style="text-align: center;">0</td> <td style="text-align: center;">0</td> <td></td> <td>Single / dual channel</td> </tr> </tbody> </table> <p>Bit 0,1: RFPGM single / dual channel mode</p> <ul style="list-style-type: none"> • 00 Receiving on single channel • 01 Reserved • 10 Reserved • 11 Receiving on dual channel (default, can be changed by <i>TR Configuration</i> in IQRF IDE) <p>Bit 4: RFPGM invoking by reset. H – enabled, L – disabled (default). This bit operates like <code>enableRFPGM / disableRFPGM</code> functions.</p> <p>Bit 6: RFPGM termination automatically ~1 minute after entering RFPGM mode. H – enabled, L – disabled (default)</p> <p>Bit 7: RFPGM termination by MCU pins RA5 or RB4. H – enabled (default), L – disabled. If enabled, the termination is invoked by log. 0 for at least ~0.25 s for single channel or ~0.5 s for dual channel on one of the dedicated pin(s):</p> <ul style="list-style-type: none"> • C5 for TR modules with multiplexed RB4 and RA5 MCU pins on the C5 SIM pad, e.g. TR-52D • Q11 or Q12 for TR-54D • Q2 or Q3 for TR-55D • Q9 or Q12 for TR-56D <p>Bits 2, 3, and 5: Must be kept cleared</p>	bit	7	6	5	4	3	2	1	0		RFPGM termination by MCU pin(s)	RFPGM termination after ~1 min	0	RFPGM enable	0	0		Single / dual channel
bit	7	6	5	4	3	2	1	0											
	RFPGM termination by MCU pin(s)	RFPGM termination after ~1 min	0	RFPGM enable	0	0		Single / dual channel											
Return value	–																		
Output values	OS is modified and setup values are applicable anytime later.																		
Preconditions	If RFPGM termination by MCU pins is enabled, both RB4 and RA5 pins must have pull-up resistors. RB4 has an internal pull-up, default enabled by OS after boot. RA5 must have an external pull-up for TR modules with not multiplexed RB4 and RA5 MCU pins on the C5 SIM pad.																		
Remarks	<ul style="list-style-type: none"> • RFPGM invoking by <code>runRFPGM()</code> is unconditional, independent on parameter x • RFPGM termination by IQRF IDE is unconditional, independent on parameter x • This function overrides the setting done by <i>TR Configuration</i> in IQRF IDE. 																		
Side effects	–																		
See also	<code>runRFPGM</code> , <code>enableRFPGM</code>																		
Example 1	<pre>void APPLICATION() setupRFPGM(0x13); // RFPGM entered: after reset or runRFPGM // RFPGM abandoned: by End RFPGM button only // Dual channel</pre>																		
Example 2	<pre>setupRFPGM(0x90); // RFPGM entered: after reset or runRFPGM // RFPGM abandoned: by dedicated pin or End RFPGM button // only // Single channel</pre>																		
Example 3	<pre>setupRFPGM(0xD3); // RFPGM entered: after reset or runRFPGM // RFPGM abandoned: by dedicated pin or End RFPGM button // or automatically ~1 min after reset // Dual channel</pre>																		

Documentation and Information

- 1 IQRF OS User's guide www.iqrf.org/155
- 2 **RAM map** and **EEPROM map**, IQRF OS User's guide, Appendix 1 [1]
- 3 **IQRF website** www.iqrf.org
- 4 **IQMESH** specification www.iqmesh.org/iqmesh
- 5 IQRF **SPI** specification www.iqrf.org/85
- 6 **IQRF support** support@iqrf.org
- 7 **TR-52D** datasheet www.iqrf.org/213
TR-54D datasheet www.iqrf.org/220
TR-55D datasheet: www.iqrf.org/239
TR-56D datasheet: www.iqrf.org/278
TR-58D-RJ datasheet: www.iqrf.org/327
- 8 **PIC16LF1938** datasheet: www.iqrf.org/214
- 9 **IQRF IDE**: www.iqrf.org/86
- 10 **Examples** (included in the StartUp Package): www.iqrf.org/112

If you need a help or more information please contact IQRF support [6]. A lot of information is also available in the IQRF OS User's guide [1] and on the IQRF home page [3].

Document revision

- 140910 A bug in `eeeReadData` and `eeeWriteData` parameters fixed.
A bug in `moduleInfo` example fixed.
- 140430 Minor improvements in functions `iqrfSleep`, `startSPI`, `sendFRC`, `responseFRC` and `setupRFPGM`.
First release for IQRF OS v3.05D

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